

Scheduling with Communication Delay in Near-Linear Time



EECS Rising Stars 2021

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Motivation

How computationally expensive is it to perform approximately-optimal scheduling?

With growing input sizes and large data centers, highly desirable to obtain a scheduling algorithm whose running time is linear in the size of the input.

All current state-of-the-art algs take super-linear time.

Problem Definition

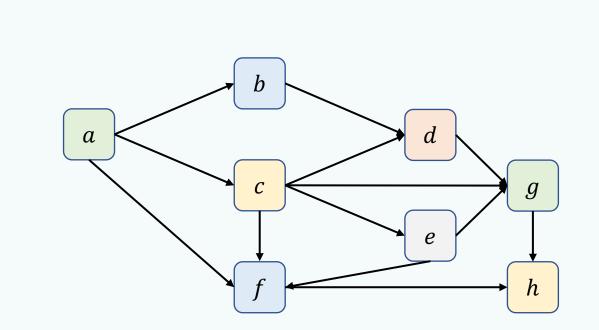
Classical scheduling problem with communication delay on identical machines, unit size jobs

Precedence-constrained jobs modeled as directed acyclic graph (DAG), vertex is job, edge indicates order

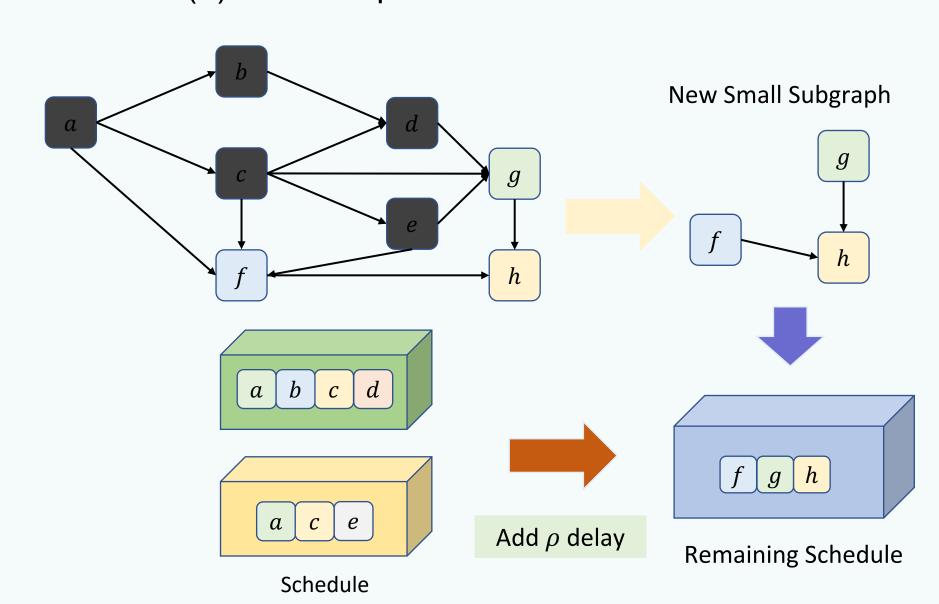
Given DAG G = (V, E), n unit-sized jobs, M identical machines and communication delay ρ , provide a near-optimal schedule in near-linear time.

Near-Linear Time Algorithm

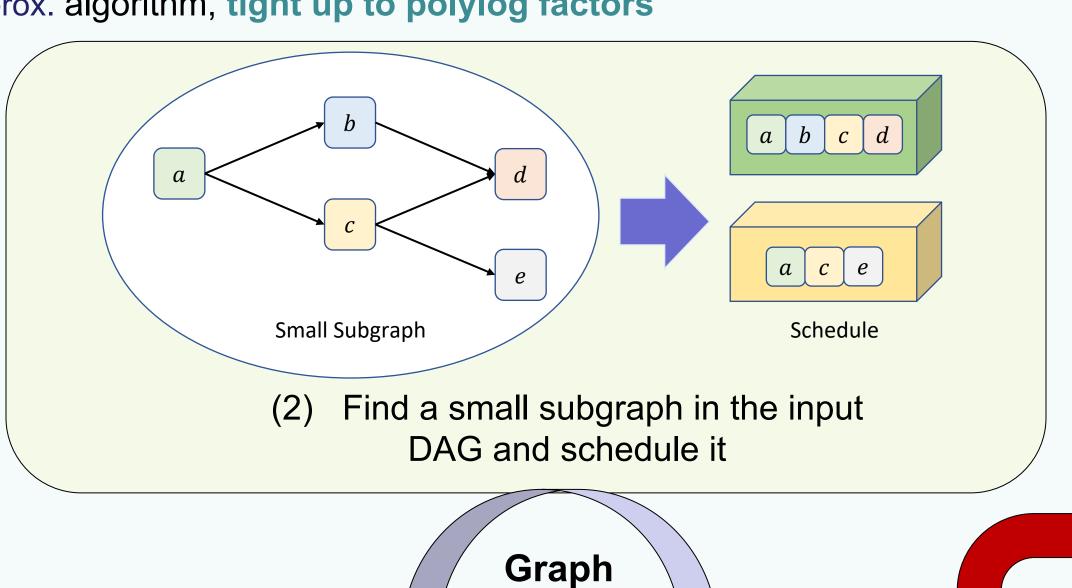
- **Previous Result:** Computing an optimal schedule is NP-hard in general. **Best previous result** by Lepere and Rapine obtain $O\left(\frac{\ln \rho}{\ln \ln \rho}\right)$ -approx. in $\Omega(m\rho + n \ln M)$ time
- Our Result: $O\left(n\ln M + \frac{m\ln^3 n\ln\rho}{\ln\ln\rho}\right)$ time and $O\left(\frac{\ln\rho}{\ln\ln\rho}\right)$ -approx. algorithm, tight up to polylog factors



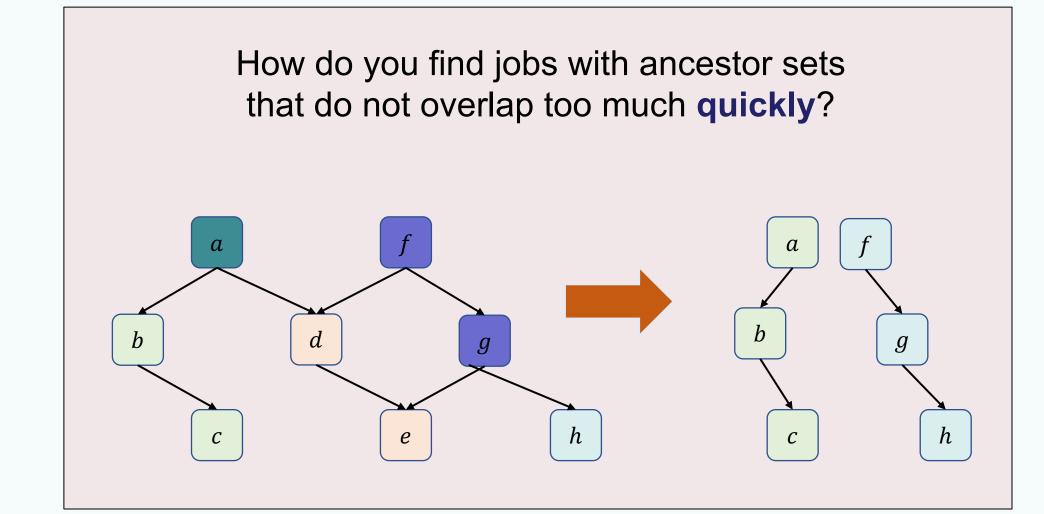
(1) Initial Input DAG



(3) Remove scheduled vertices from the graph. Add a ρ communication delay to schedule after previously scheduled jobs. Find a new small subgraph and schedule it.



Problem!

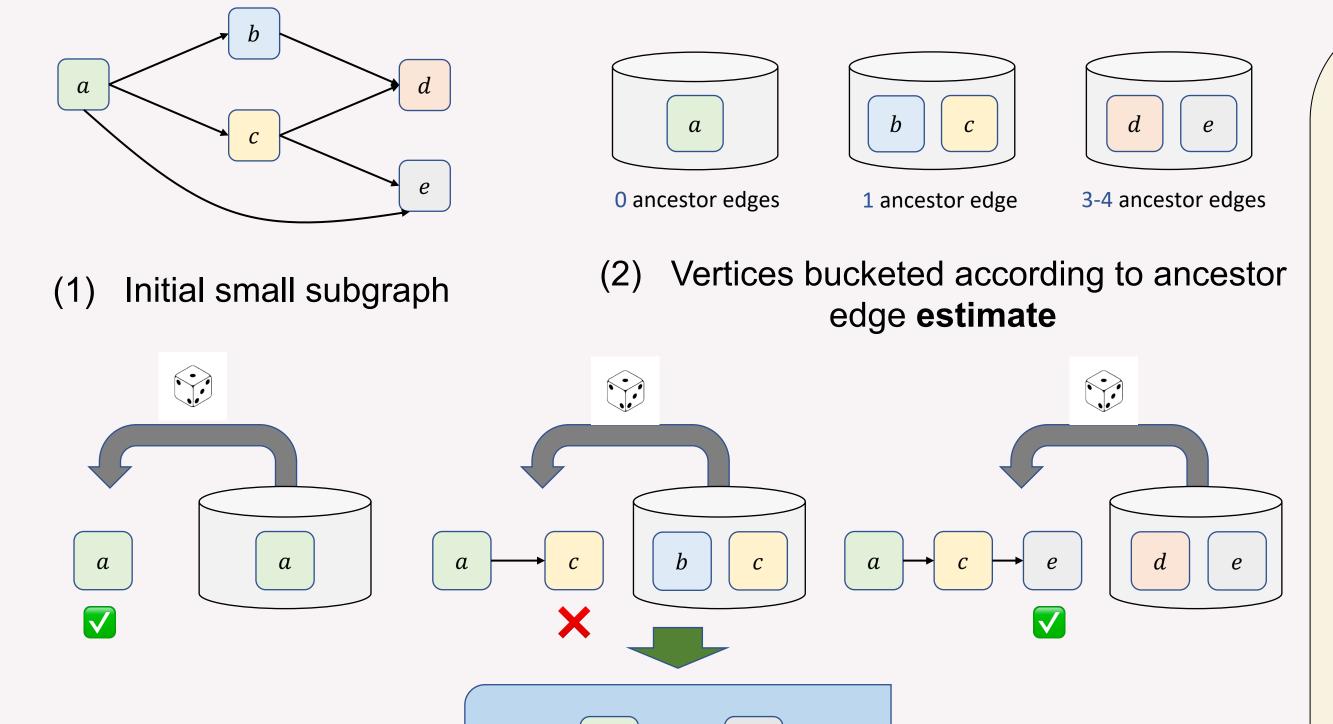


[Lepere and Rapine] Renaud Lepere and Christophe Rapine. An asymptotic O(In ρ/In In ρ)-approximation algorithm for the scheduling problem with duplication on large communication delay graphs. In STACS, volume 2285 of Lecture Notes in Computer Science, pages 154–165, 2002.

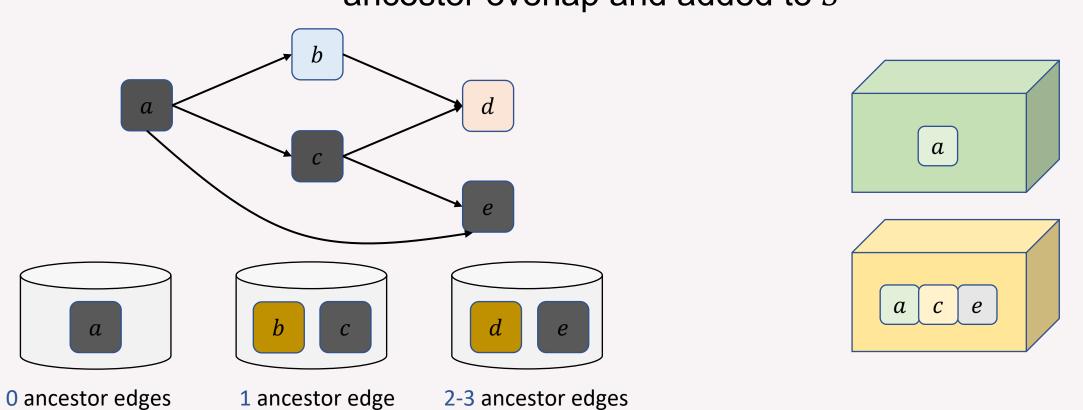
[Graham] R. L. Graham. Bounds on multiprocessing anomalies and related packing algorithms. In Proceedings of the May 16-18, 1972, Spring Joint Computer Conference, AFIPS '72 (Spring), page 205–217, New York, NY, USA, 1971. Association for Computing Machinery.

Scheduling Small Subgraphs

Small Subgraph: A subgraph of the input DAG where each vertex has at most $\rho - 1$ ancestors



3) Vertices **uniformly-at-random sampled from bucket**, checked for ancestor overlap and added to *S*



(5) Pruning vertices with large overlap with S

(6) List scheduling jobs in S

- Estimating Number of Ancestor Edges: We use count-distinct estimators to estimate the number of ancestors and edges in the induced subgraph of each node and its ancestors
- * Partitioning Vertices to Buckets: First partition vertices into $O(\log \rho)$ buckets based on ancestor edge estimates
- ❖ Sampling Vertices from Buckets: Vertices (and ancestors) are sampled from buckets and added to S if its ancestors do not overlap too much with S. Keep sampling until we've seen O(log n) vertices in a row that we do not add to S or bucket is empty.
- Pruning All Stale Vertices from Buckets: Vertices with ancestor sets that overlap too much with S are pruned or removed from buckets
- Standard list scheduling jobs in S: Duplicate all ancestors of a job, schedule a job and all its (duplicated) ancestors on the same machine

Analysis Key Insights

- **Estimating Number of Ancestor Edges:** Our **count-distinct estimator algorithm on DAGs** return $(1 \pm \epsilon)$ -approximations to the number of ancestors (and edges) with probability at least $1 \frac{1}{n^d}$ for any constant $d \ge 1$ in $O\left(\frac{1}{\epsilon^2}\log^2 n\right)$ time per vertex
- **Partitioning Vertices to Buckets:** A vertex v is in the i-th bucket if the estimate of the number of edges in the induced subgraph of its ancestors, $\hat{e}(v)$, is in $[2^i, 2^{i+1}]$; we can partition all vertices in $O\left(\frac{m+n}{c^2}\log^2 n\right)$ time
- **Sampling Vertices from Buckets:** A sampled vertex v and all its ancestors **are added to** S if at least a γ fraction of its ancestor set is not in S. Once we stop sampling, **less than a constant fraction of the vertices remaining** in each bucket can be added to S (for any constant)
- Pruning All Stale Vertices from Buckets: All vertices that cannot be added to S are pruned; any pruned vertex has at most a 4γ-fraction of ancestors not in S
- * Standard list scheduling jobs in S: Graham's list scheduling algorithm where scheduling |S| jobs requires $O(|S| \log M)$ time