

CPSC 768: Scalable and Private Graph Algorithms

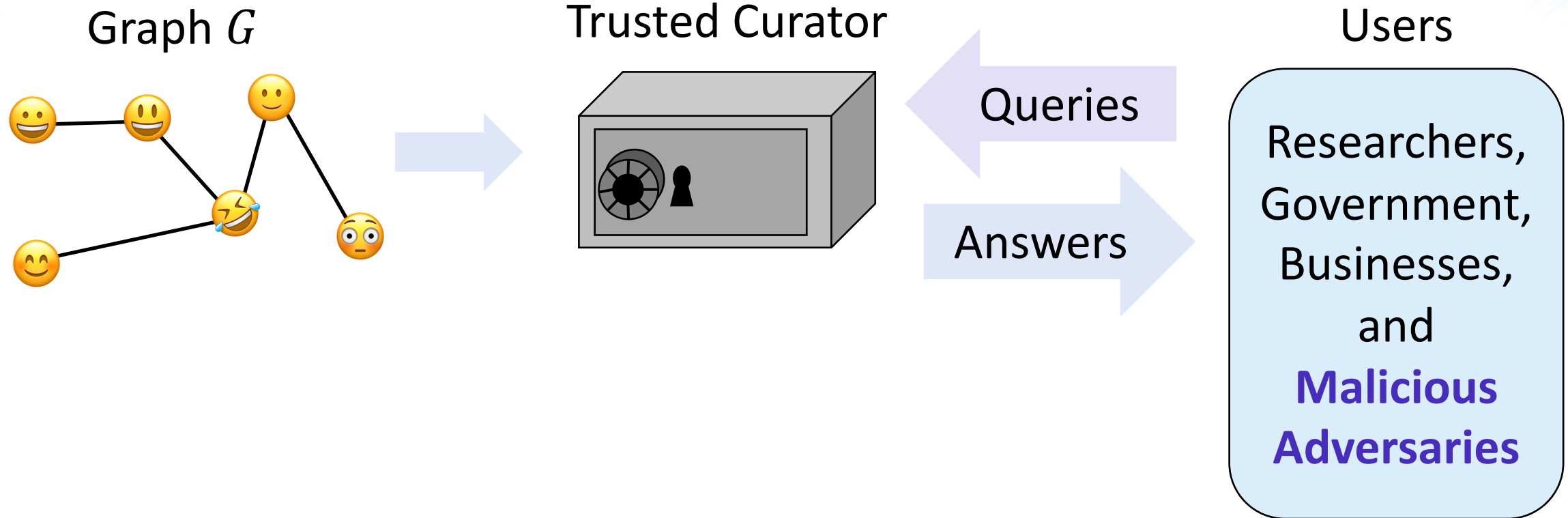
Lecture 11 and 12: Differential Privacy Tools and Graphs

Quanquan C. Liu
quanquan.liu@yale.edu

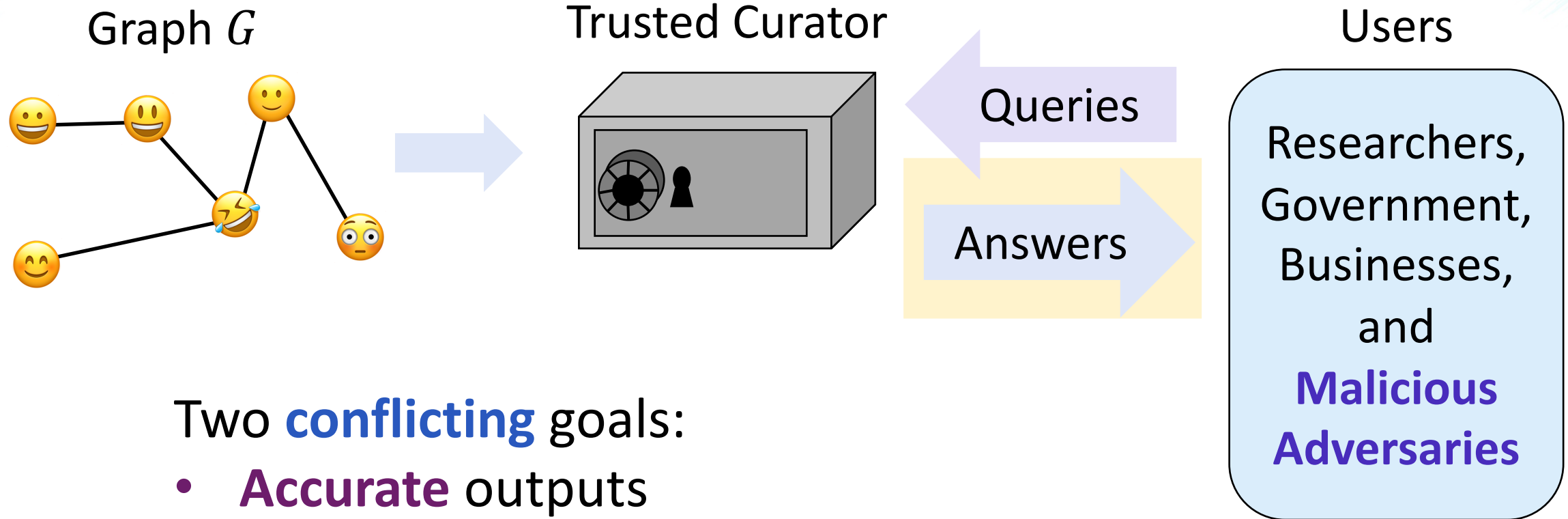
Announcements

- Check the latest announcement on Canvas:
 - Scheduling Lectures survey: due **Feb. 26**
 - Final Project Proposal: due **Feb. 29, one page**
 - Final Project Examples
- Open problem sessions:
 - Link for joining CPSC 768 Slack
 - Open Problem Session food orders

Private Analysis of Graph Data



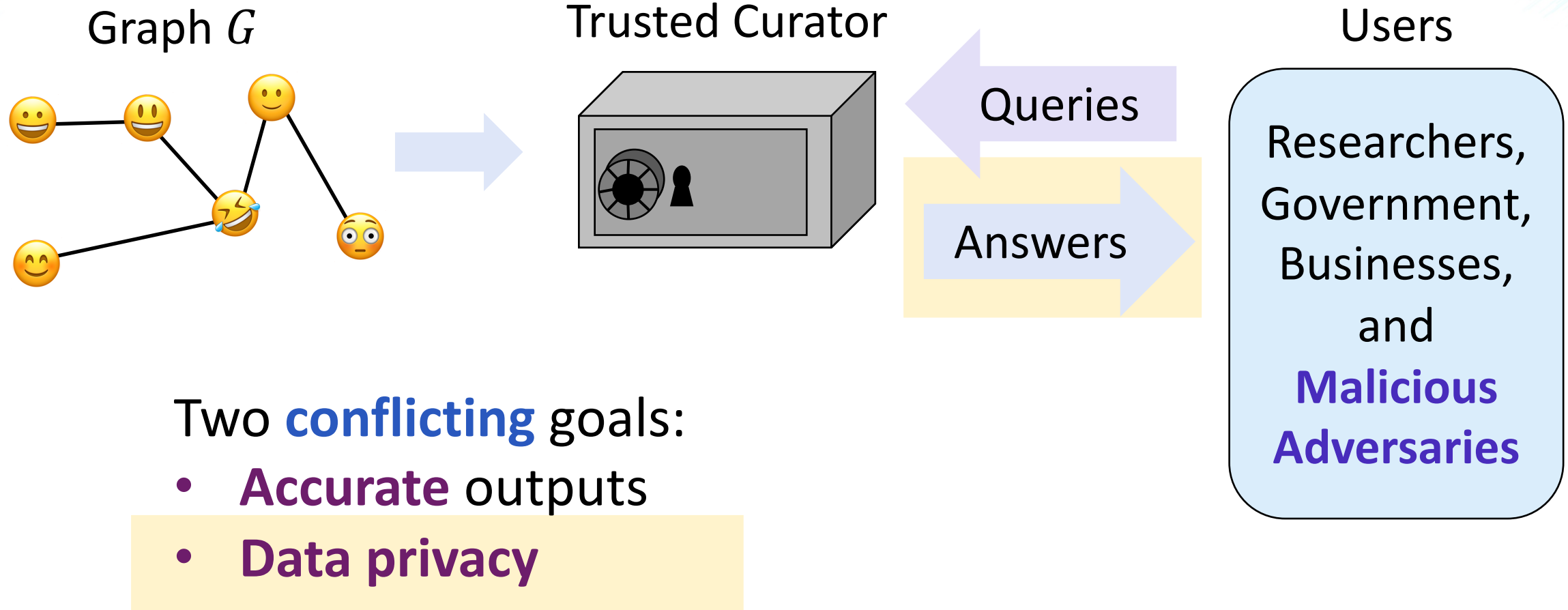
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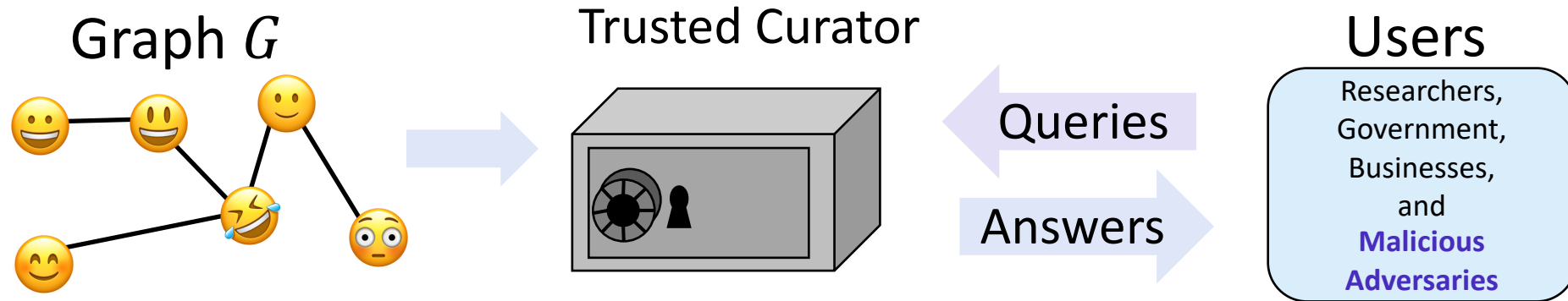
Two **conflicting** goals:

- **Accurate** outputs
- **Data privacy**

Private Analysis of Graph Data



(Central Model of) Differential Privacy



- **Neighboring** inputs differ in some information we'd like to hide

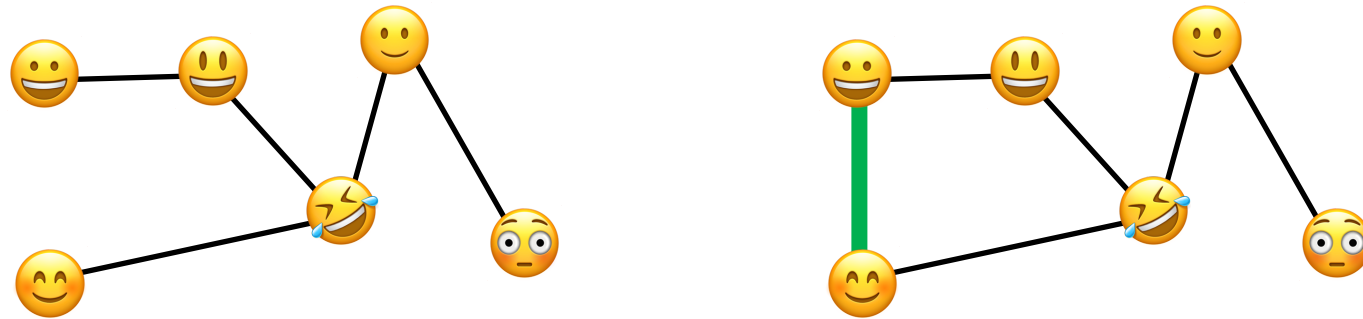
Differential Privacy [Dwork-McSherry-Nissim-Smith '06]

An algorithm \mathcal{A} is **ϵ -differentially private** if for all pairs of neighbors G and G' and all sets of possible outputs S :

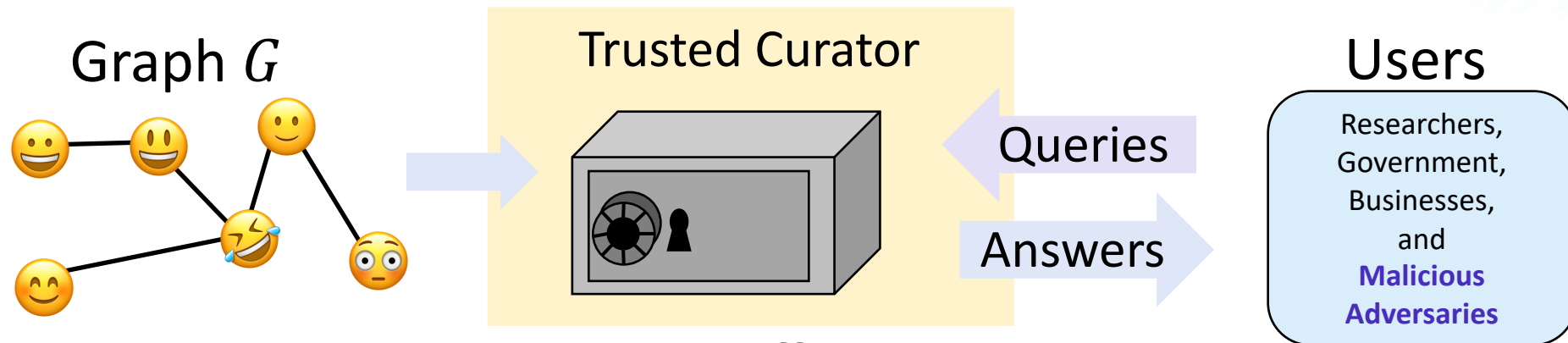
$$\Pr[\mathcal{A}(G) \in S] \leq e^\epsilon \cdot \Pr[\mathcal{A}(G') \in S].$$

Edge-Neighboring Graphs

- **Edge-neighboring** graphs: differ in **one edge**



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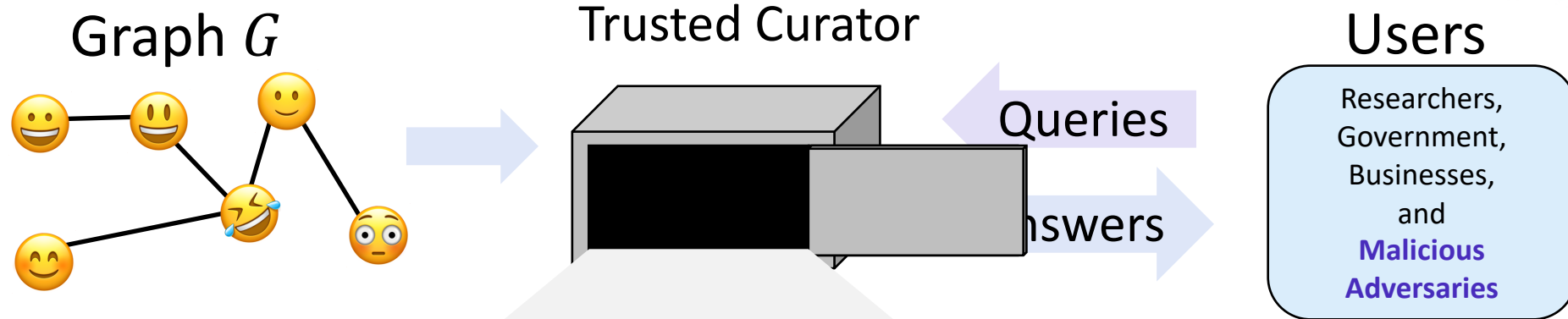
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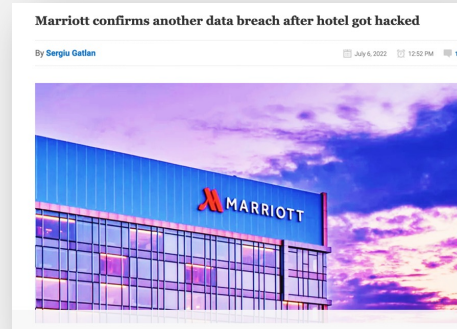
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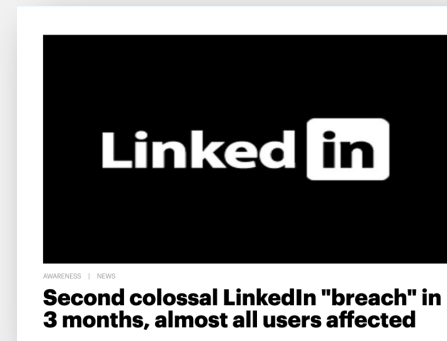
(Central Model of) Differential Privacy



<https://www.npr.org/2021/04/09/986005820/after-data-breach-exposes-530-million-facebook-says-it-will-not-notify-users>

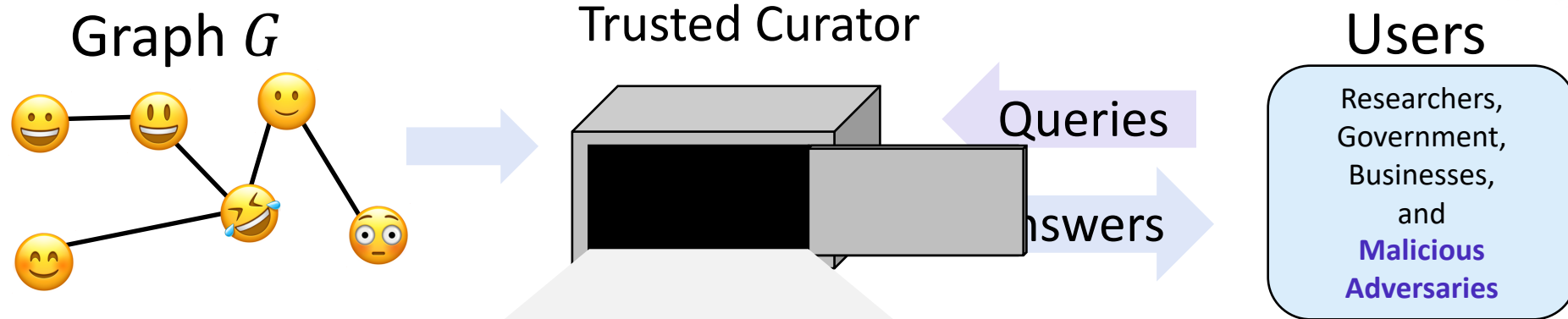


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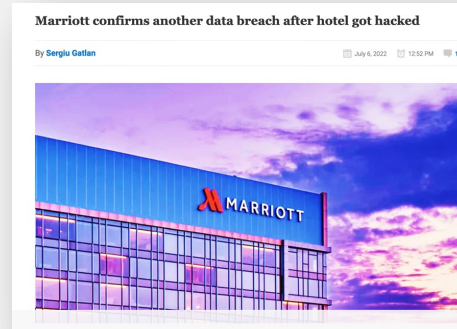


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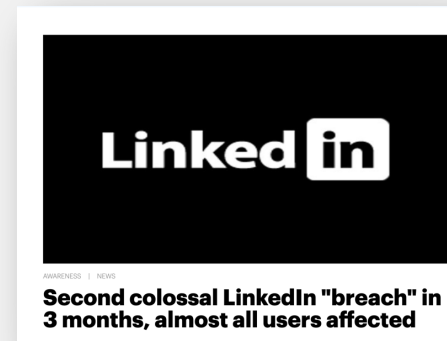
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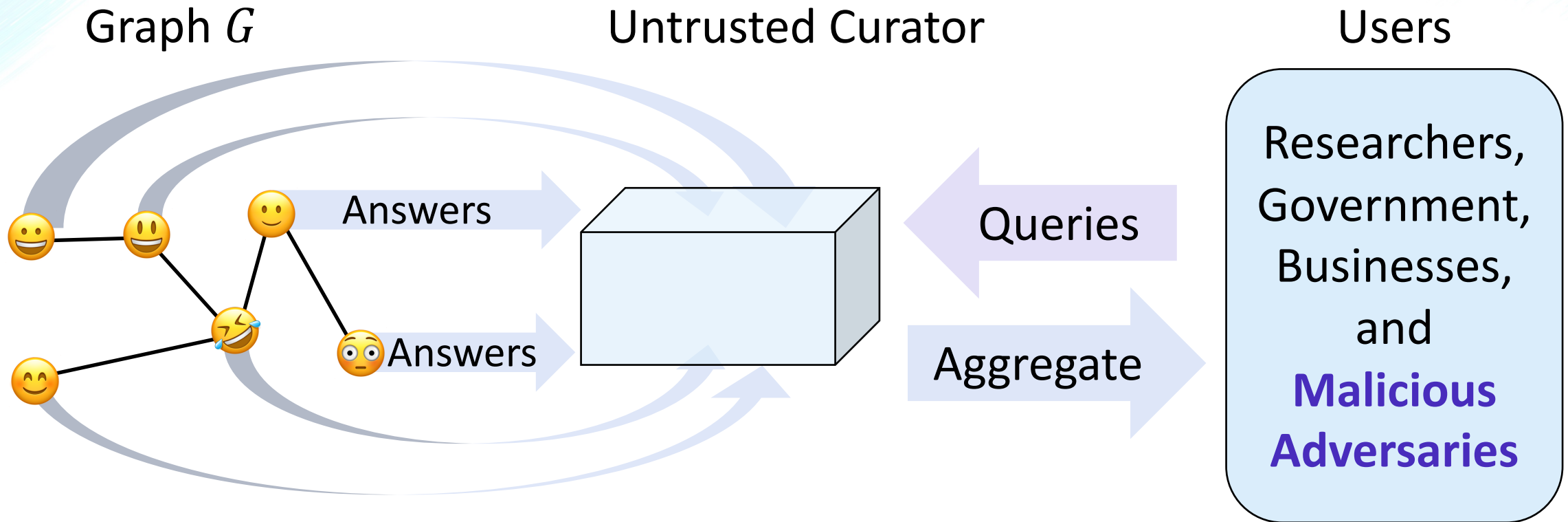
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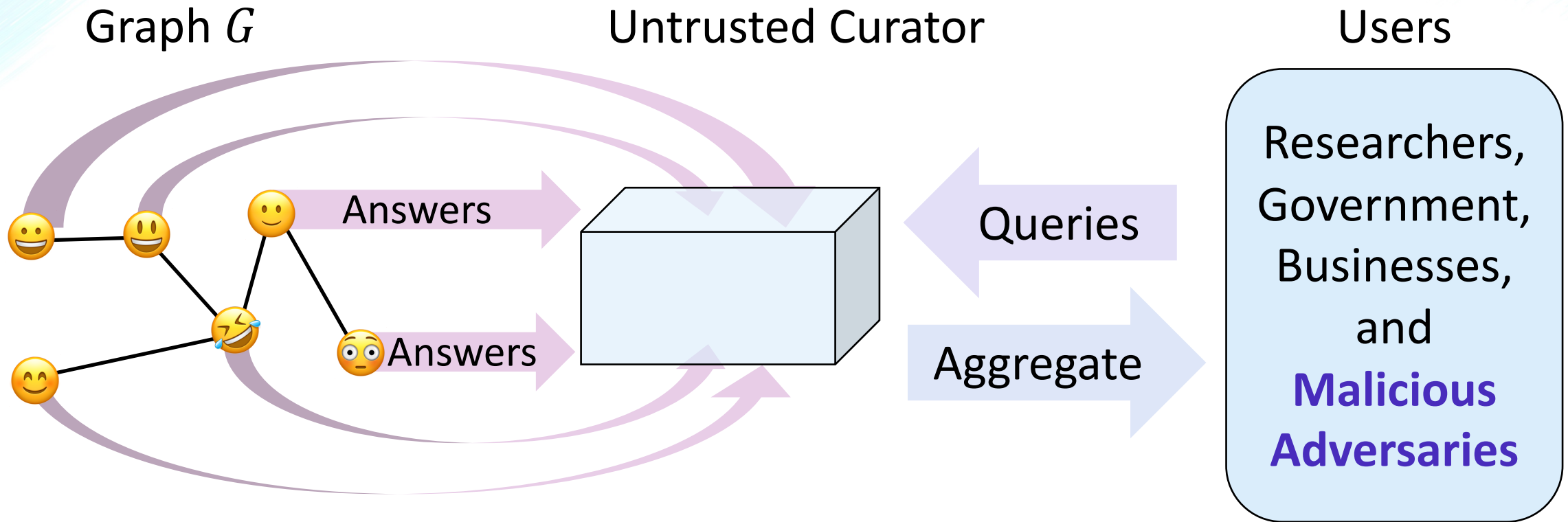
**Unrealistic trust
in trusted curator**

Weaker Notion of Trust: **Local Model**



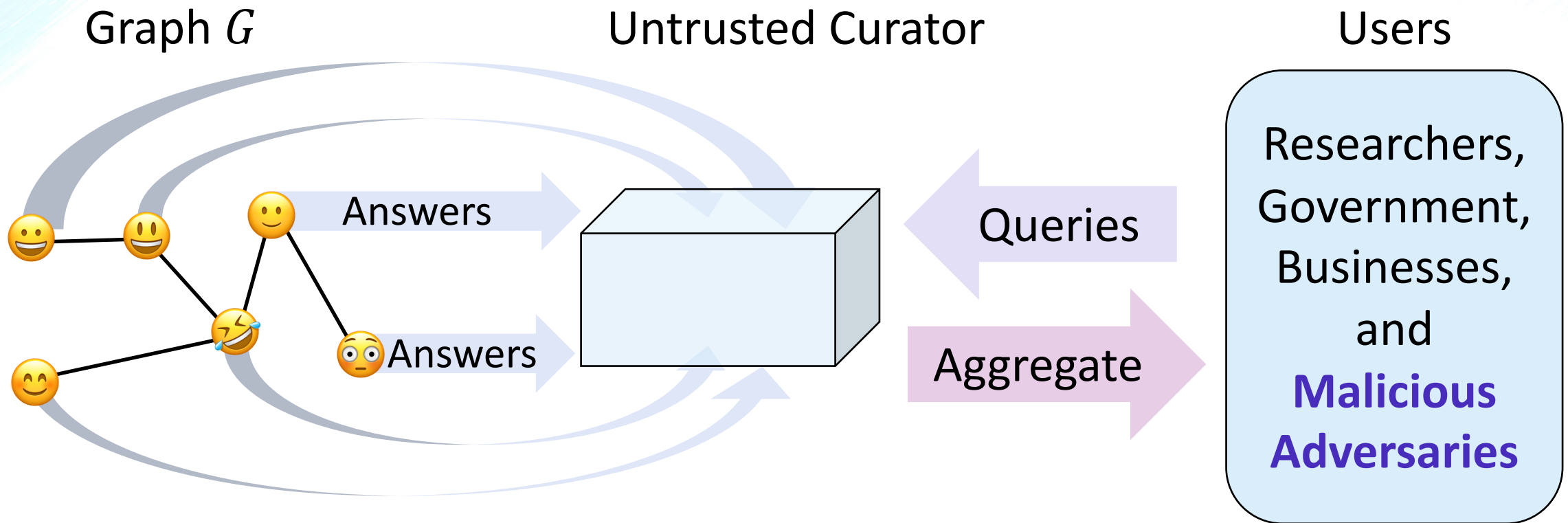
- **Each node publishes privatized** output
- Curator computes aggregated statistics using outputs

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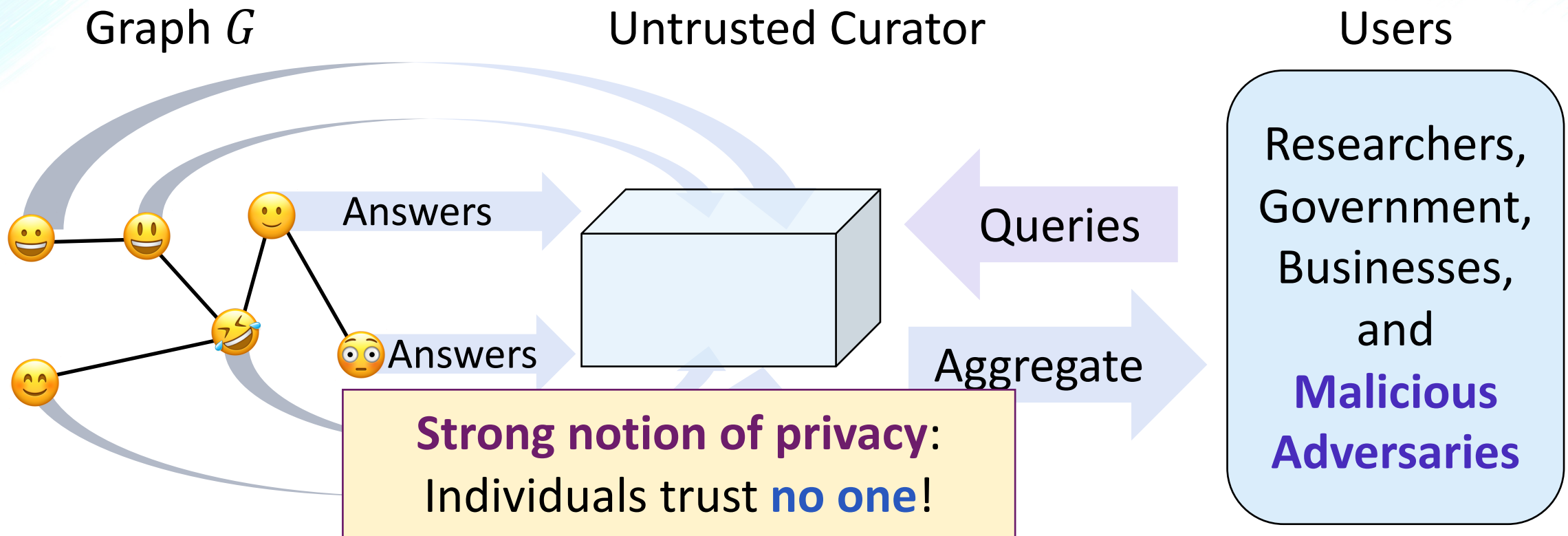
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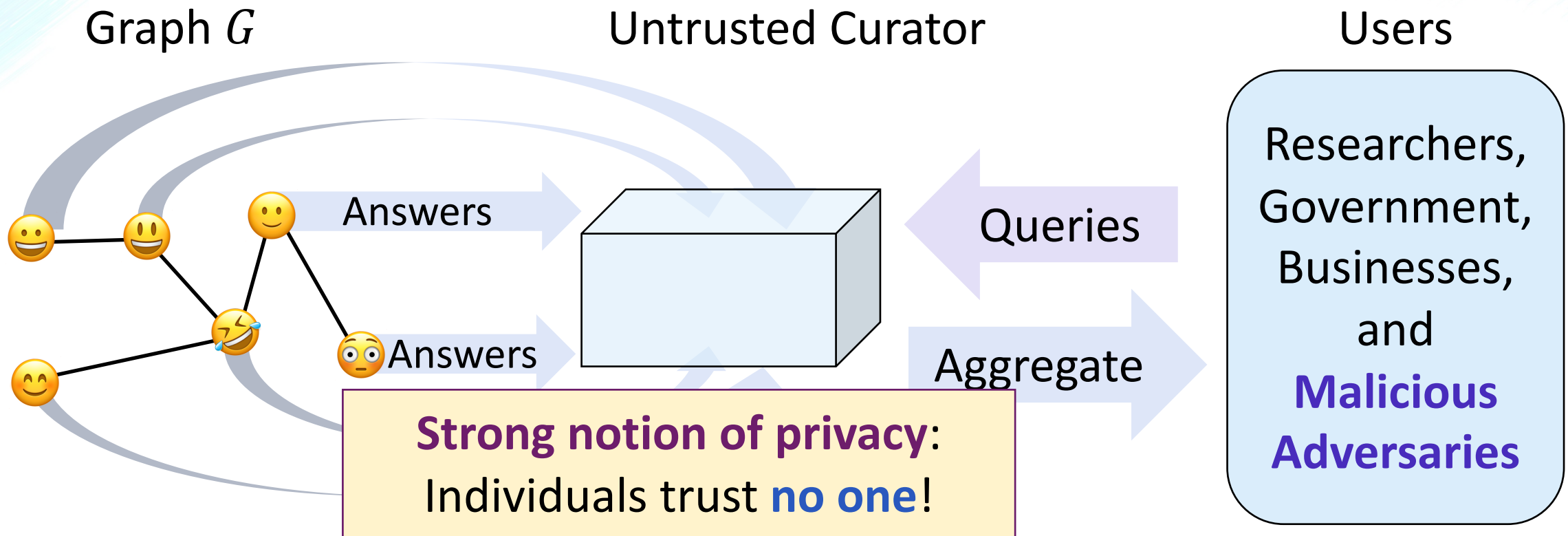
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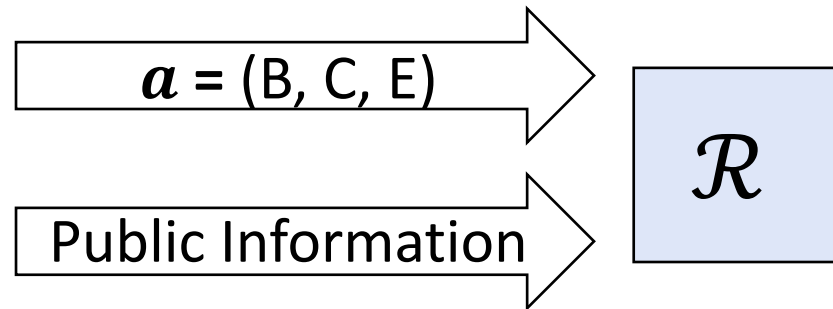
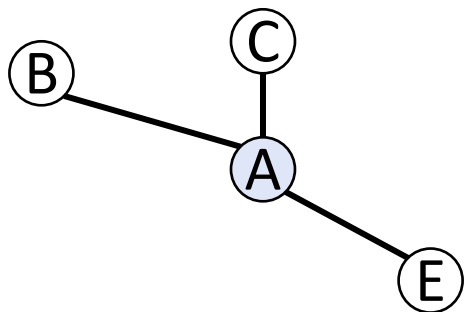
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Local Edge Differential Privacy (LEDP)

Local Randomizer

[Adapted from Kasiviswanathan-Lee-Nissim-Raskhodnikova-Smith '11]

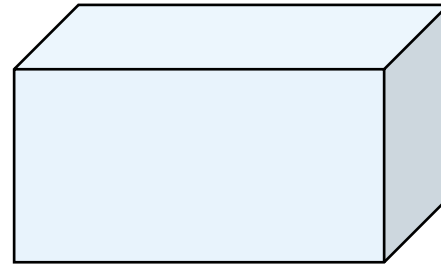
An **ϵ -local randomizer** \mathcal{R} is an ϵ -differentially private algorithm that takes as input an adjacency list \mathbf{a} and public information.



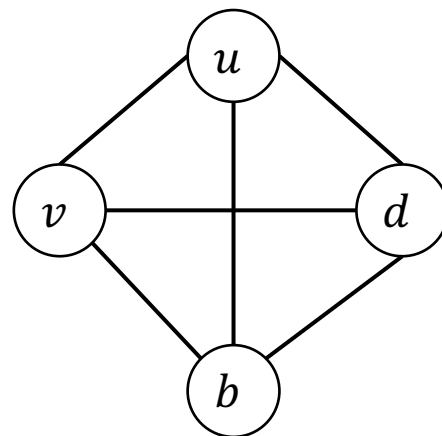
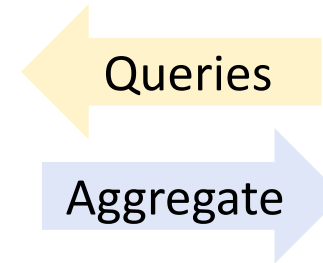
Local Edge Differential Privacy (LEDP)

Algorithm proceeds in **rounds**
in **distributed graph** using
local randomizers

Untrusted Curator



Users

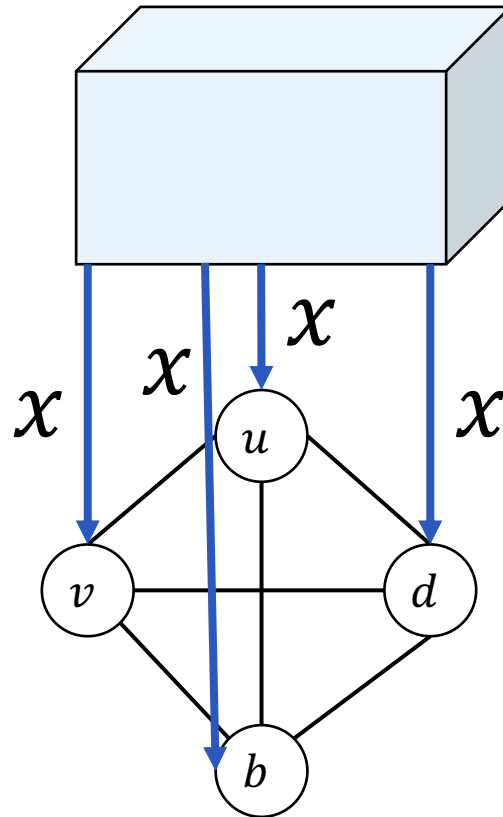


Round 1

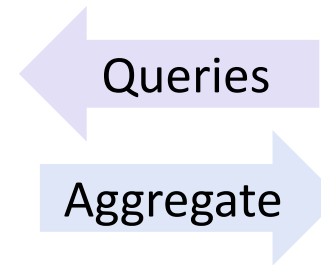
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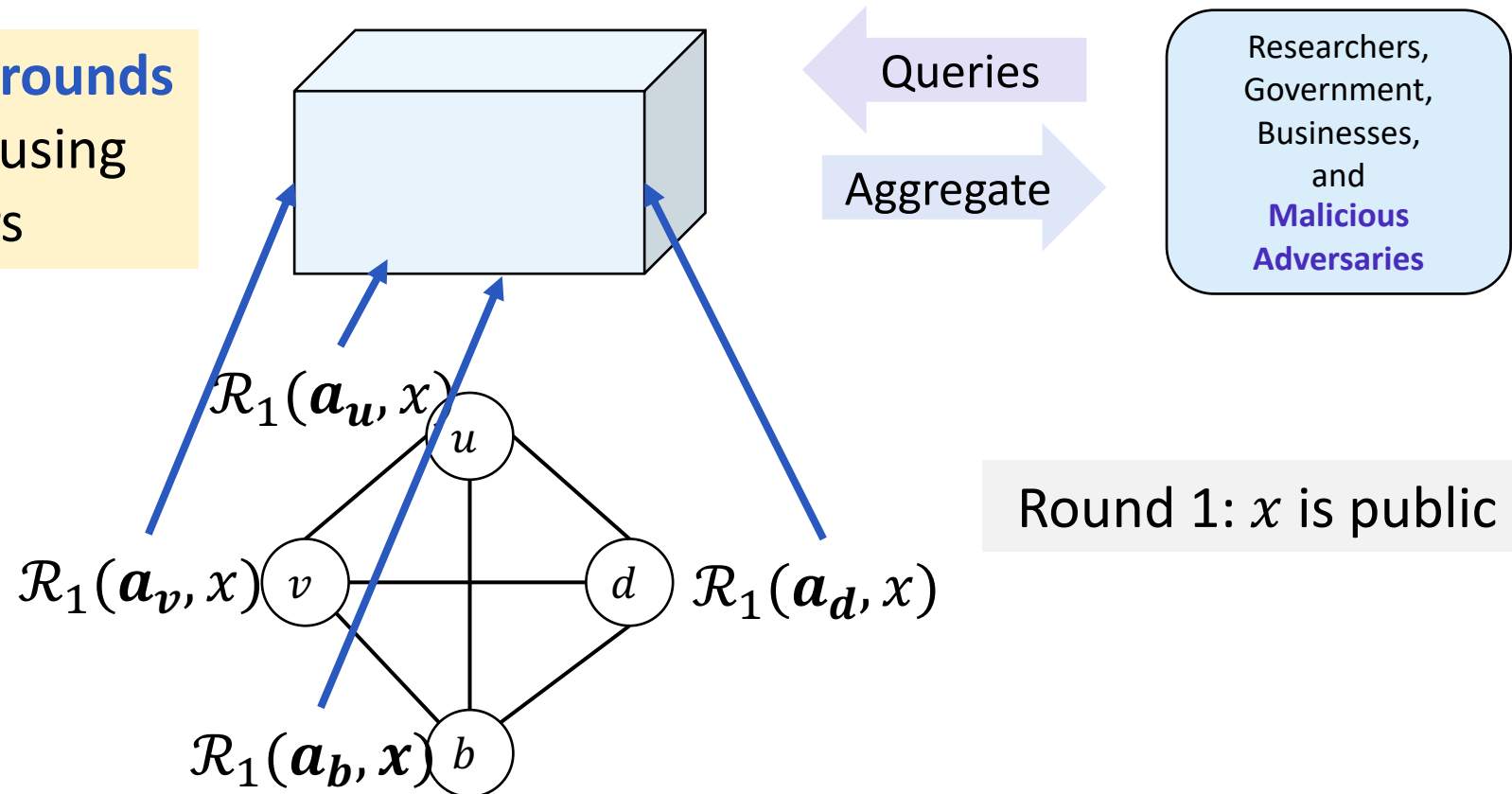
Round 1

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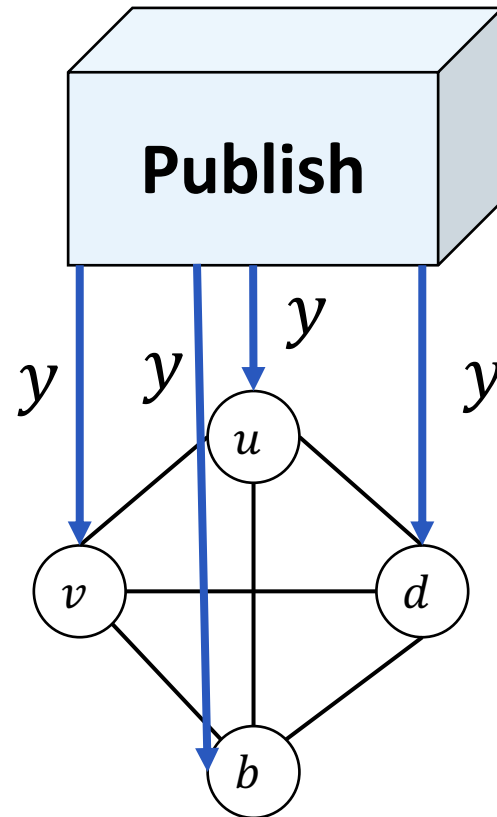
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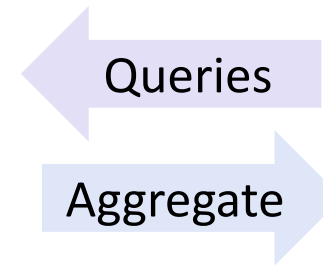
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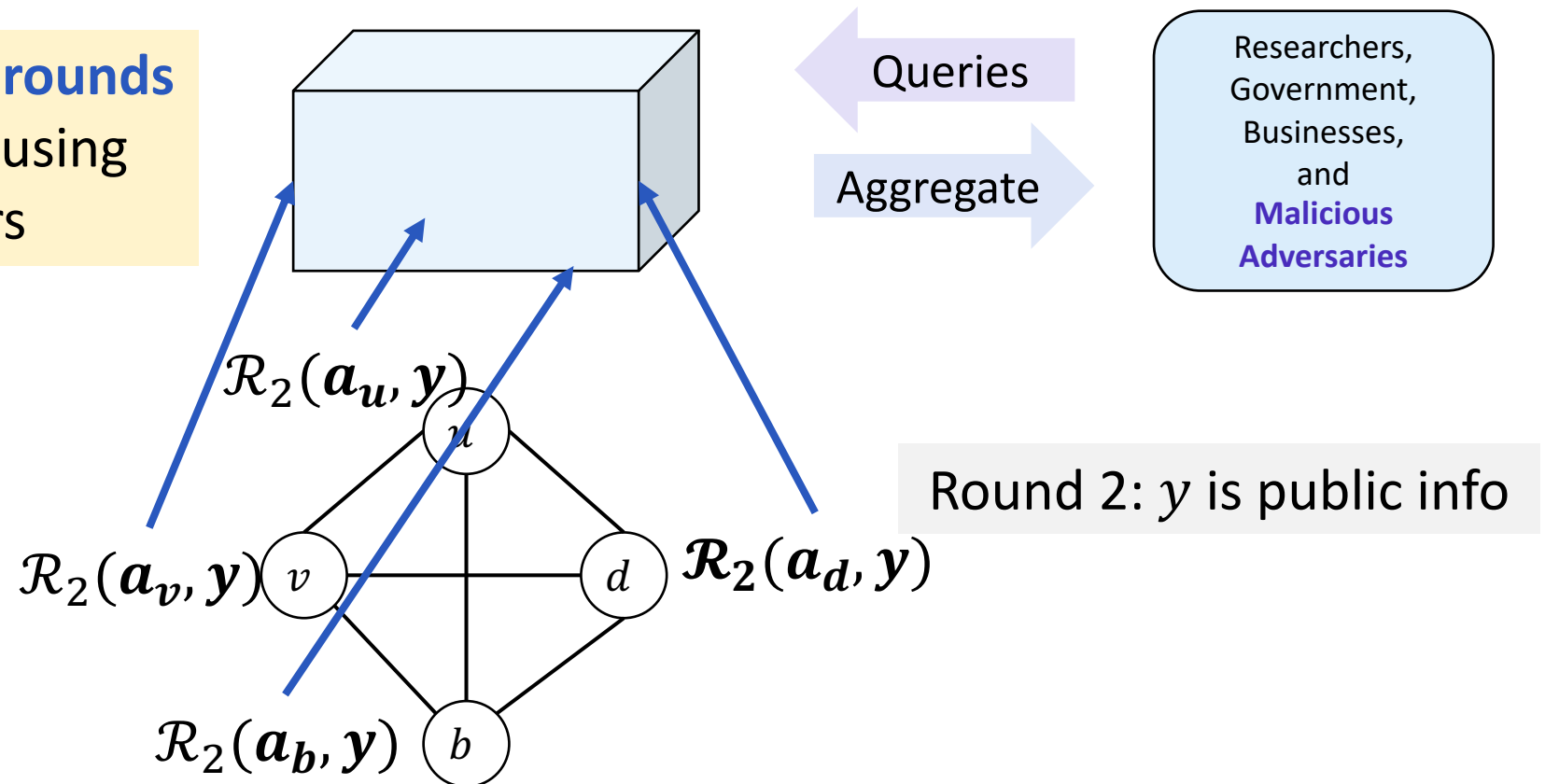
Round 2: y is public info

Local Edge Differential Privacy (LEDP)

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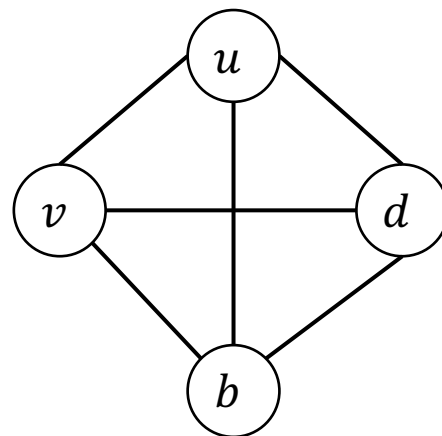
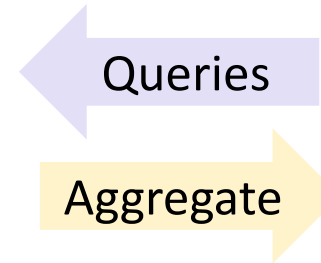
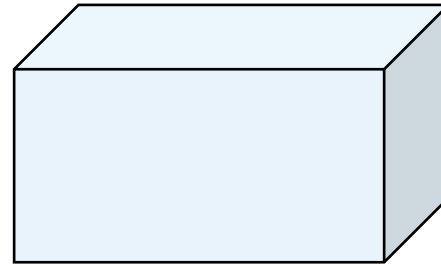


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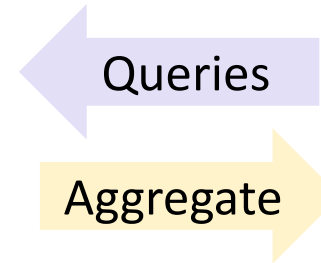
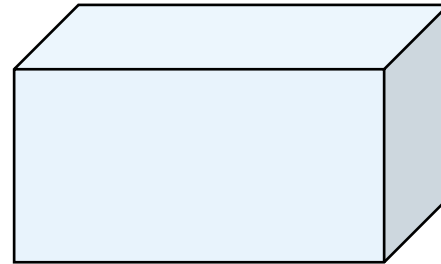
Round 2

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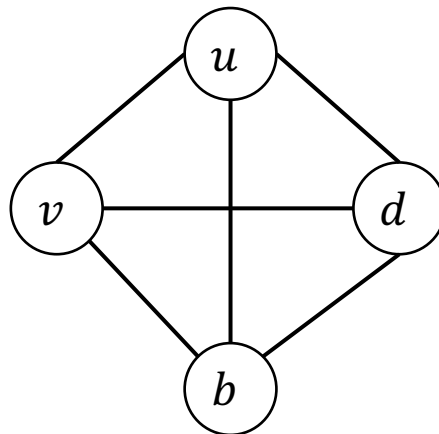
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Relevant Complexity Measure:
Number of Rounds of Communication



Round 2

Local Edge Differential Privacy (LEDP)

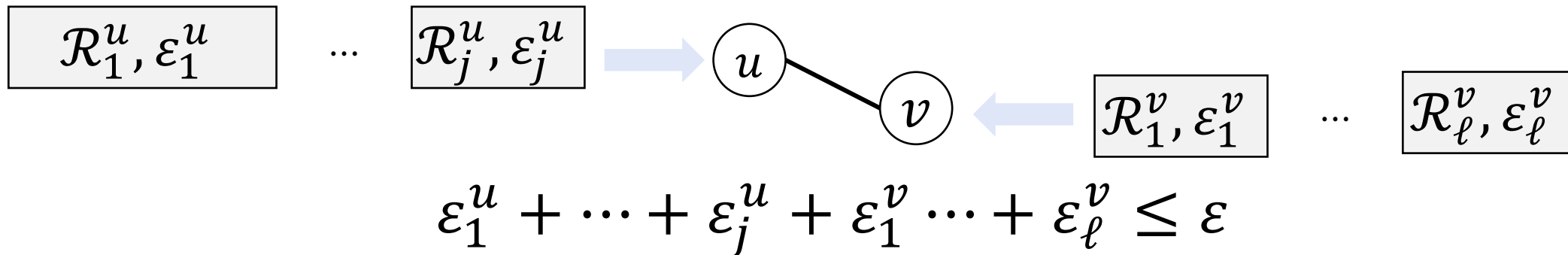
Local Edge Differential Privacy

[DLRSSY '22 Adapted from Kasiviswanathan-Lee-Nissim-Raskhodnikova-Smith '11]

Let algorithm \mathcal{A} use (potentially different) local randomizers $\mathcal{R}_1^u, \dots, \mathcal{R}_j^u$ and $\mathcal{R}_1^v, \dots, \mathcal{R}_\ell^v$ on nodes u, v with privacy parameters $\varepsilon_1^u, \dots, \varepsilon_j^u$ and $\varepsilon_1^v, \dots, \varepsilon_\ell^v$.

\mathcal{A} is **ε -local edge differentially private (ε -LEDP)** if for every edge $\{u, v\}$,

$$\varepsilon_1^u + \dots + \varepsilon_j^u + \varepsilon_1^v + \dots + \varepsilon_\ell^v \leq \varepsilon.$$



Related Work

- **Local edge differentially private algorithms:**
 - Relatively **new direction**
 - **k -Core Decomposition, Densest Subgraphs, Low Out-degree Ordering:** [Dhulipala-Liu-Raskhodnikova-Shi-Shun-Yu '22, Dinitz-Kale-Lattanzi-Vassilvitskii '23, Dhulipala-Li-Liu '23]
 - **Triangle and other subgraph counting:** [Imola-Murakami-Chaudhuri '21, '22; Eden-Liu-Raskhodnikova-Smith '23]
 - **Other graph problems** in empirical settings in “decentralized” privacy models [Sun-Xiao-Khalil-Yang-Qin-Wang-Yu '19; Qin-Yu-Yang-Khalil-Xiao-Ren '17; Gao-Li-Chen-Zou '18; Ye-Hu-Au-Meng-Xiao '20]

Randomized Response

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- Randomly report the same bit or flipped bit:
 - $Y_i = \begin{cases} X_i & \text{w. p. } 1/2 + \varepsilon \\ 1 - X_i & \text{w. p. } 1/2 - \varepsilon \end{cases}$

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- Geometric mechanism: $O\left(\frac{1}{\varepsilon}\right)$ error but not locally private

Locally Private Triangle Counting

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Central DP vs. LEDP

Locally Private Triangle Counting

Central DP vs. LEDP

**Triangle
Counting**

DP Upper Bound

$O\left(\frac{n}{\epsilon}\right)$ additive error
(trivial)

LEDP Lower Bound

$\Omega\left(\frac{n^{3/2}}{\epsilon}\right)$ additive error
(multiple rounds)

$\Omega\left(\frac{n^2}{\epsilon}\right)$ additive error
(one round)

[Eden-Liu-Raskhodnikova-Smith ICALP '23]

One-Round Locally Private Triangle Counting [Eden-Liu-Raskhodnikova-Smith '23]

- **Input:** Graph $G = ([n], E)$ represented by $n \times n$ adjacency matrix A with entries $a_{ij}, \epsilon > 0$

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**Each node holds
their own adjacency
list as private info**

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Releasing noisy upper triangular matrix

1	0	1
0	1	0
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 - For all $\{i, j, k\} \in \binom{[n]}{3}$, set $Z_{i,j,k} \leftarrow Y_{i,j} \cdot Y_{j,k} \cdot Y_{i,k}$

Normalized $Y_{i,j}$ so that $E[Z_{i,j,k}] = 1$ if triangle exists and 0 otherwise

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Therefore, $E[\hat{T}] = T$

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 - Then, $E[Y_{i,j}] = E\left[\frac{(X_{i,j} \cdot (e^\epsilon + 1) - 1)}{e^\epsilon - 1}\right] = \frac{(E[X_{i,j}] \cdot (e^\epsilon + 1) - 1)}{e^\epsilon - 1}$

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- If $\{i, j\} \in E$, then $\frac{E[X_{i,j}] \cdot (e^\varepsilon + 1) - 1}{e^\varepsilon - 1} = \frac{\left(\left(\frac{e^\varepsilon}{e^\varepsilon + 1}\right) \cdot (e^\varepsilon + 1) - 1\right)}{e^\varepsilon - 1} = \frac{(e^\varepsilon - 1)}{e^\varepsilon - 1} = 1$

Analysis of the Expectation and Variance

- Proof:

- If $\{i, j\} \in E$, then $E[X_{i,j}] = \frac{e^\varepsilon}{e^\varepsilon + 1}$; otherwise $E[X_{i,j}] = \frac{1}{e^\varepsilon + 1}$

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- If $\{i, j\} \notin E$, then $\frac{E[X_{i,j}] \cdot (e^\varepsilon + 1) - 1}{e^\varepsilon - 1} = \frac{\left(\left(\frac{1}{e^\varepsilon + 1}\right) \cdot (e^\varepsilon + 1) - 1\right)}{e^\varepsilon - 1} = 0$

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- Linearity of expectations gives $E[\hat{T}] = E\left[\sum_{ijk \in [n]^3} Z_{i,j,k}\right] = T$

Analysis of the Expectation and Variance

- **Lemma:** Returns an approximate \hat{T} where $\text{Var}[\hat{T}] = \Theta\left(\frac{C_4}{\varepsilon^2} + \frac{n^3}{\varepsilon^6}\right)$
- Proof:
 - $\text{Var}[X_{i,j}]?$

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- **Lemma:** Returns an approximate \hat{T} where $\text{Var}[\hat{T}] = \Theta\left(\frac{C_4}{\varepsilon^2} + \frac{n^3}{\varepsilon^6}\right)$

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Bernoulli variable

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$e^\varepsilon \in [1, 3)$ for
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$$E[U_{i,j,k}] = 0 \text{ and } \text{Var}[U_{i,j,k}] = \text{Var}[Z_{i,j,k}]$$

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Non-zero covariance: share an edge; how many?

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Non-zero covariance: share an edge; number of 4-cycles

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$$\begin{aligned} \text{Var}\left[\sum_{\{i,j,k\} \in \binom{[n]}{3}} U_{i,j,k}\right] &\leq \sum_{\{i,j,k\} \in \binom{[n]}{3}} \Theta\left(\frac{1}{\varepsilon^6}\right) \\ &\quad + \sum_{\{i,j,k,l\} \in C_4} E[U_{i,j,k} \cdot U_{j,k,l}] \end{aligned}$$

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$$\sum_{\{i,j,k,l\} \in C_4} E[U_{i,j,k} \cdot U_{j,k,l}] \leq \sum_{\{i,j,k,l\} \in C_4} E[Y_{i,j} \cdot Y_{j,k}^2 \cdot Y_{i,k} \cdot Y_{l,j} \cdot Y_{l,k}]$$

$$\leq \sum_{\{i,j,k,l\} \in C_4} E[Y_{j,k}^2]$$

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On Wednesday, more DP mechanisms!

- Laplace mechanism
- (Geometric mechanism—already discussed)
- Exponential mechanism
- Gaussian mechanism
- Privacy amplification via subsampling

CPSC 768: Scalable and Private Graph Algorithms

Lecture 12: Differential Privacy Mechanisms

Quanquan C. Liu
quanquan.liu@yale.edu

Announcements

- Check the latest announcement on Canvas:
 - Scheduling Lectures survey: due **Feb. 26**
 - Final Project Proposal: due **Feb. 29, one page (email to me)**
 - Final Project Examples
- Open problem sessions:
 - Link for joining CPSC 768 Slack
 - Open Problem Session food orders

Global Sensitivity

- **Intuition**: Measure of how different the output of a function is on neighboring input

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Definition (Global Sensitivity): The global sensitivity of a function: $f: G \rightarrow R$ is defined as:

$$\Delta_f = \max_{\{G \sim G'\}} (|f(G) - f(G')|)$$

where G and G' are edge-neighboring graphs.

Global Sensitivity Examples

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- What is the global sensitivity of the following problems (assuming for each we have a function that gives the exact solution):
 - Triangle counting
 - Maximum matching
 - Average Degree

Global Sensitivity Examples

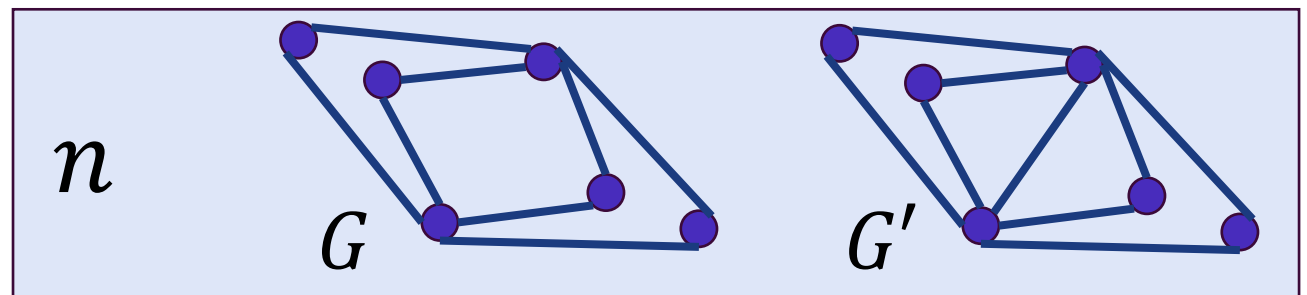
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Global Sensitivity Examples

Definition (Global Sensitivity): The global sensitivity of a function: $f: G \rightarrow R$ is defined as:

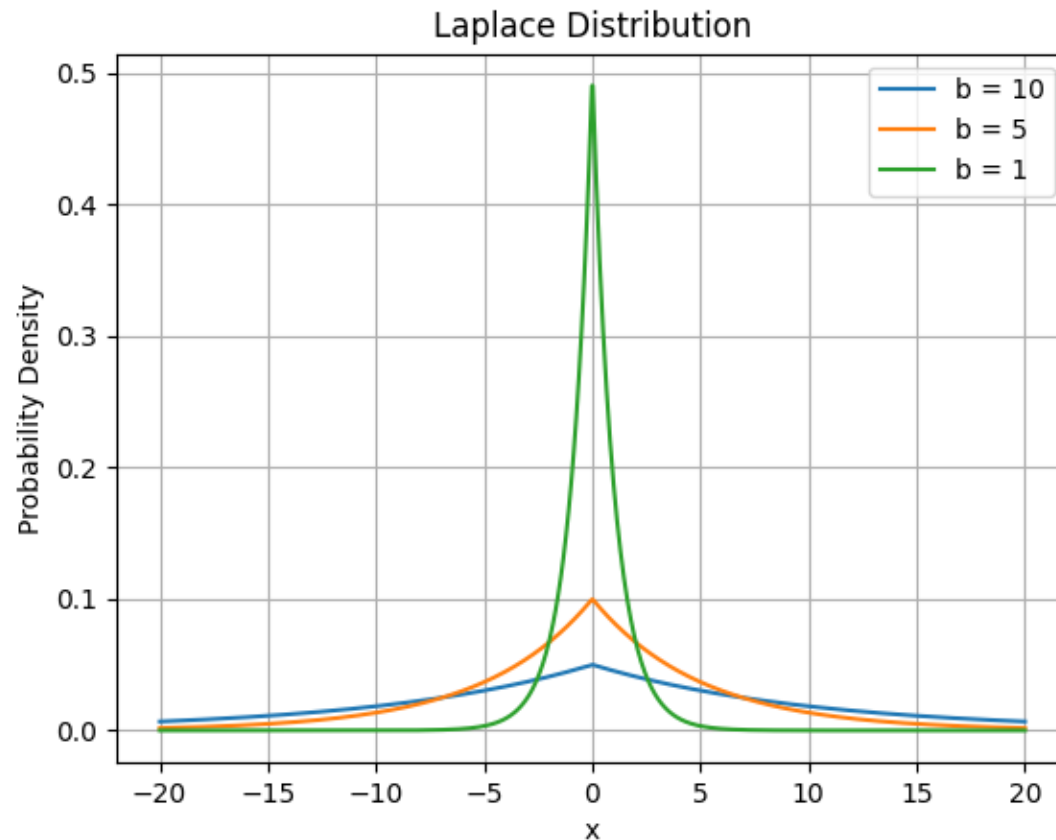
$$\Delta_f = \max_{\{G \sim G'\}} (|f(G) - f(G')|)$$

where G and G' are edge-neighboring graphs.

- What is the global sensitivity of the following problems (assuming for each we have a function that gives the exact solution):
 - Triangle counting: n
 - Maximum matching: 1
 - Average Degree: $2/n$

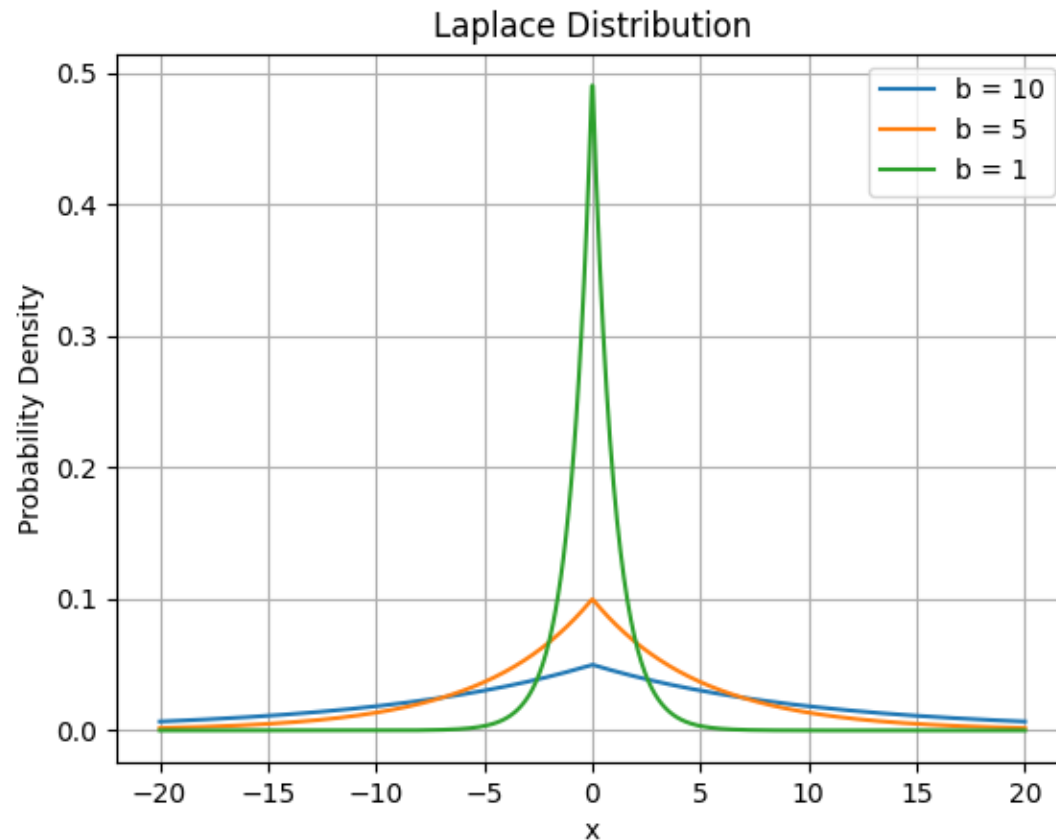
Laplace Distribution

- The PDF of $X \in R$ is: $\text{Lap}(b) = \frac{1}{2b} \cdot \exp\left(-\left(\frac{|X|}{b}\right)\right)$



Laplace Distribution

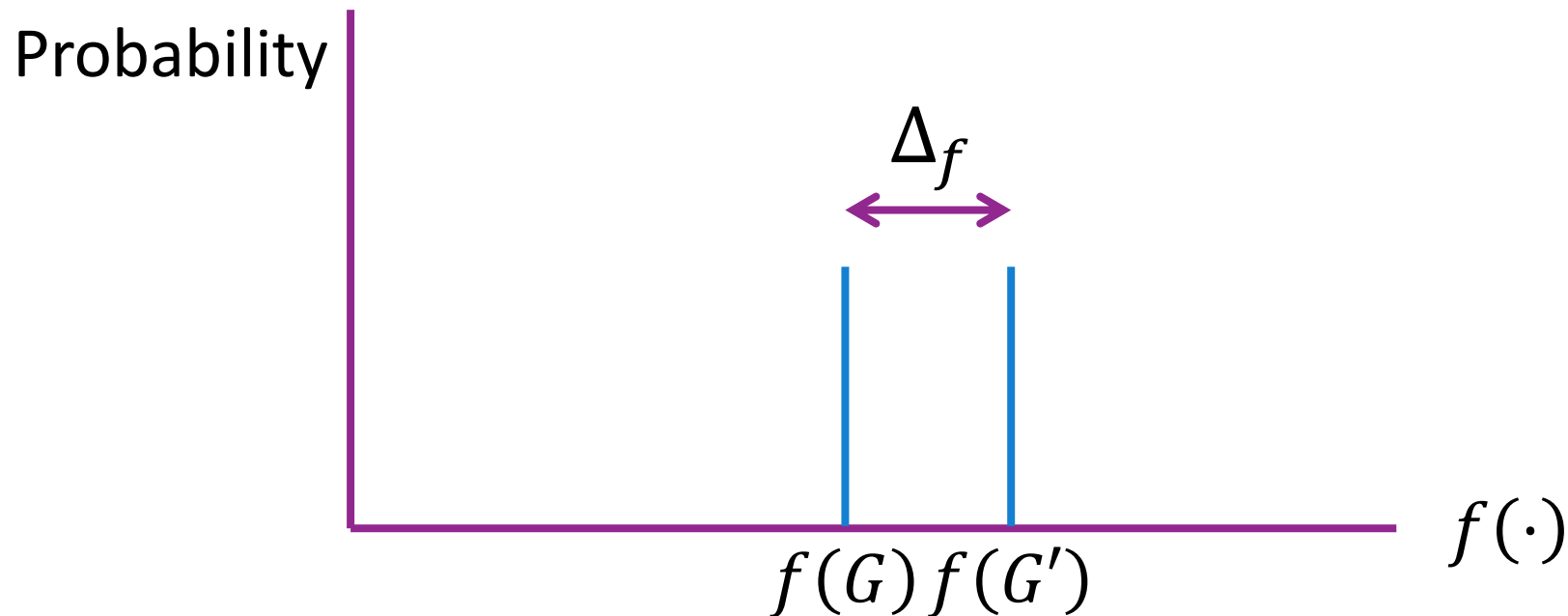
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Larger b
heavier tails

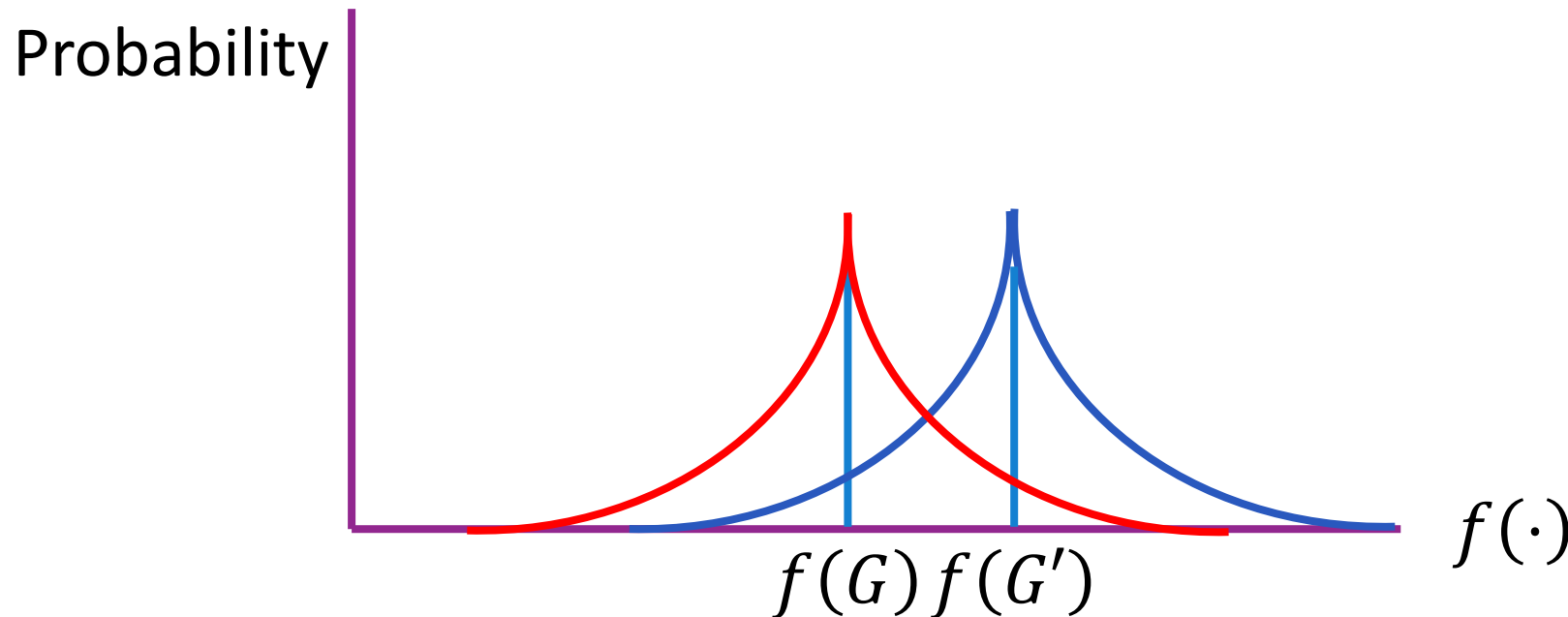
Laplace Mechanism

- Lemma: Given a function $f: G \rightarrow R$ with sensitivity Δ_f ,
 $f(G) + \text{Lap}\left(\frac{\Delta_f}{\epsilon}\right)$ is ϵ -differentially private.
- Intuition: Solution for G and G' differ by Δ_f



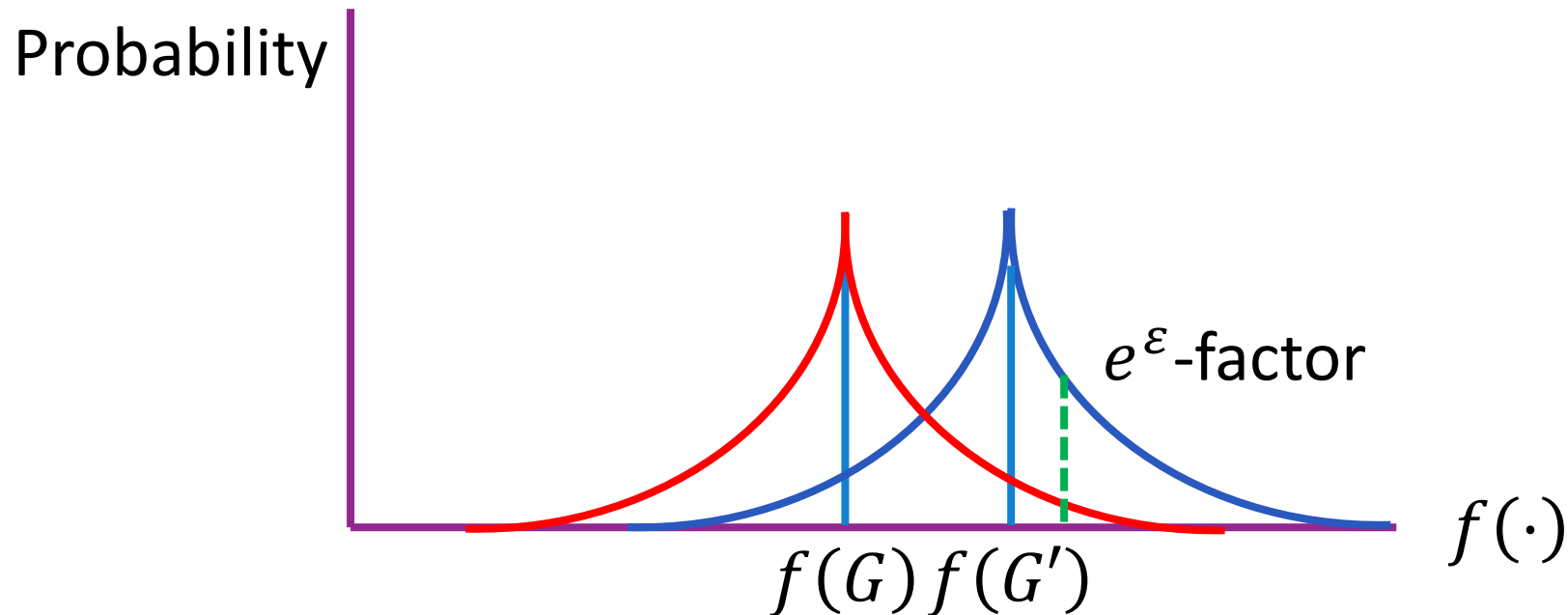
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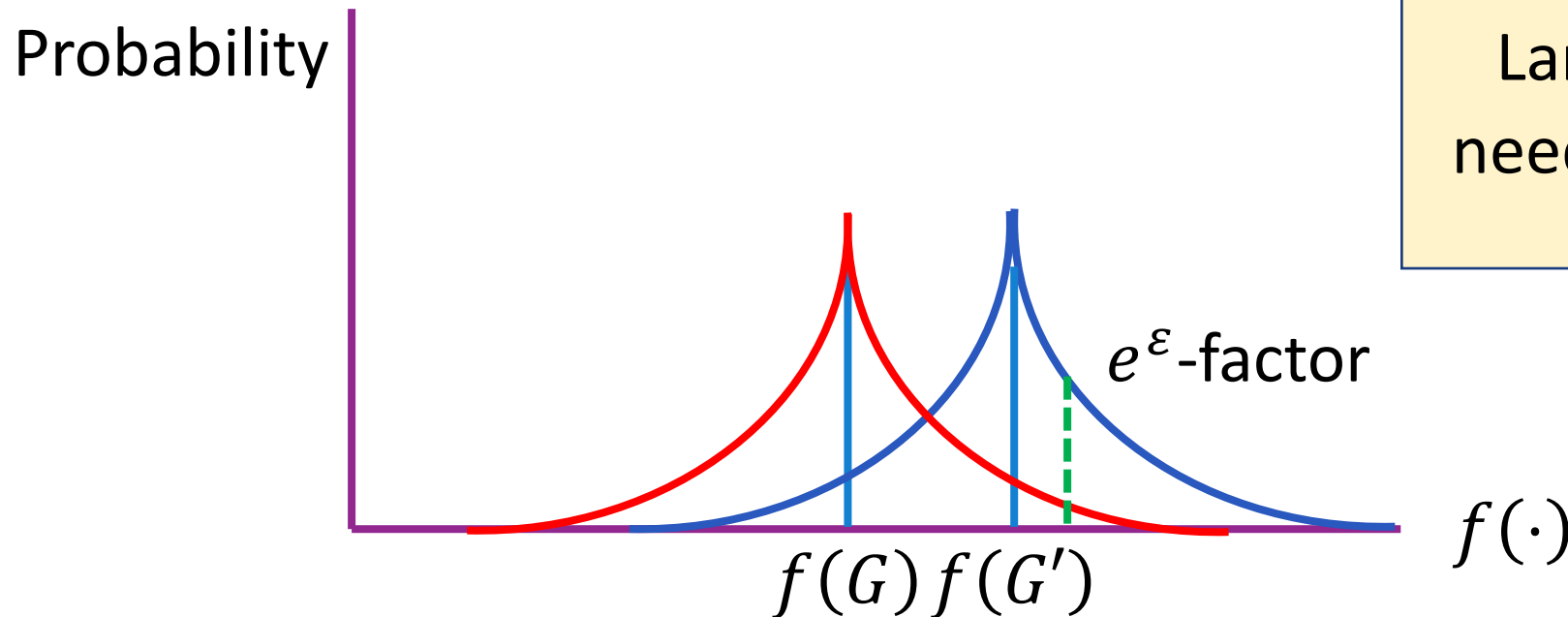
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Larger Δ_f means
need a flatter curve

Laplace Mechanism

- Lemma: Given a function $f: G \rightarrow R$ with sensitivity Δ_f ,

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- Proof: Consider neighboring graphs G and G' and function $f: G \rightarrow R$. Let p and p' denote the probability density functions of $f(G) + \text{Lap}\left(\frac{\Delta_f}{\epsilon}\right)$ and $f(G') + \text{Lap}\left(\frac{\Delta_f}{\epsilon}\right)$, respectively. Then, for an arbitrary point $z \in R$:

$$\frac{p(z)}{p'(z)} = \frac{\exp\left(-\frac{\epsilon|f(G) - z|}{\Delta_f}\right)}{\exp\left(-\frac{\epsilon|f(G') - z|}{\Delta_f}\right)}$$

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- Proof:

$$\begin{aligned} &= \exp\left(-\frac{\epsilon(|f(G') - z| - |f(G) - z|)}{\Delta_f}\right) \\ &\leq \exp\left(-\frac{\epsilon(|f(G') - f(G)|)}{\Delta_f}\right) \\ &\leq \exp\left(-\frac{\epsilon\Delta_f}{\Delta_f}\right) = \exp(\epsilon) \end{aligned}$$

By the triangle inequality

Laplace Mechanism Accuracy

- Lemma: Given a function $f: G \rightarrow R$ with sensitivity Δ_f , let $M(G) = f(G) + \text{Lap}\left(\frac{\Delta_f}{\epsilon}\right)$, then $P\left(|M(G) - f(G)| \leq \frac{\Delta_f}{\epsilon} \log\left(\frac{1}{\delta}\right)\right) \geq 1 - \delta$

Laplace Mechanism Accuracy

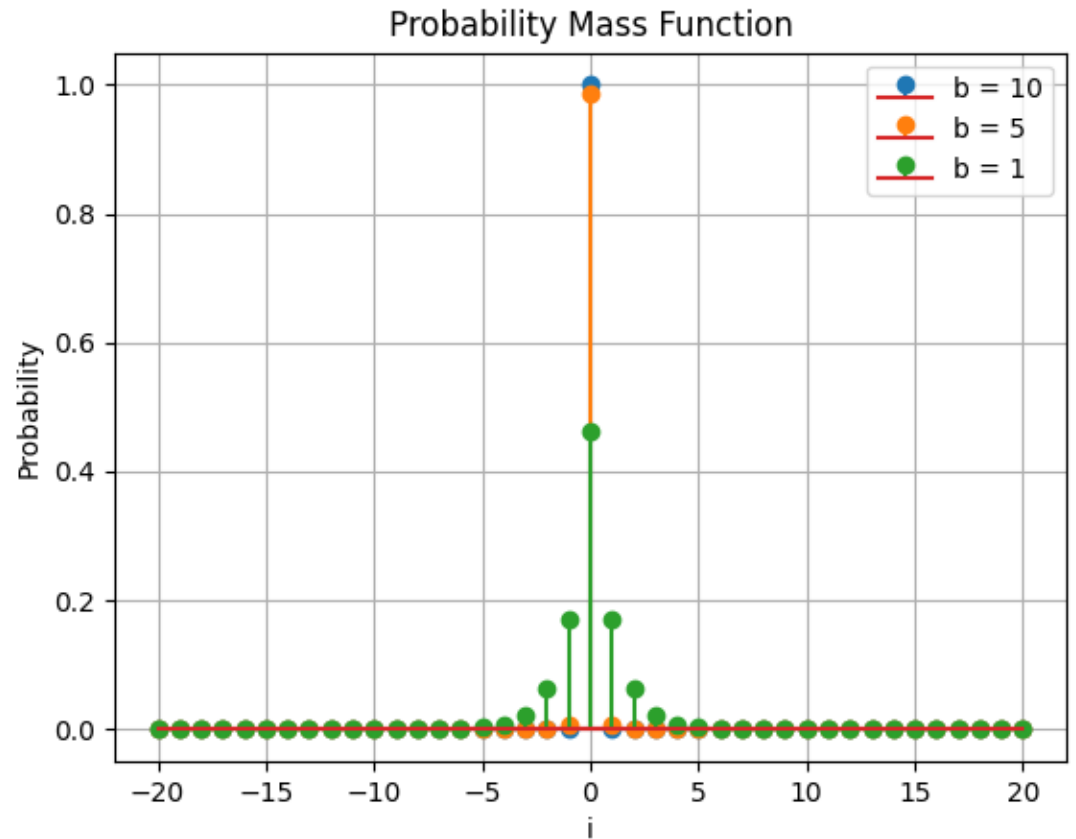
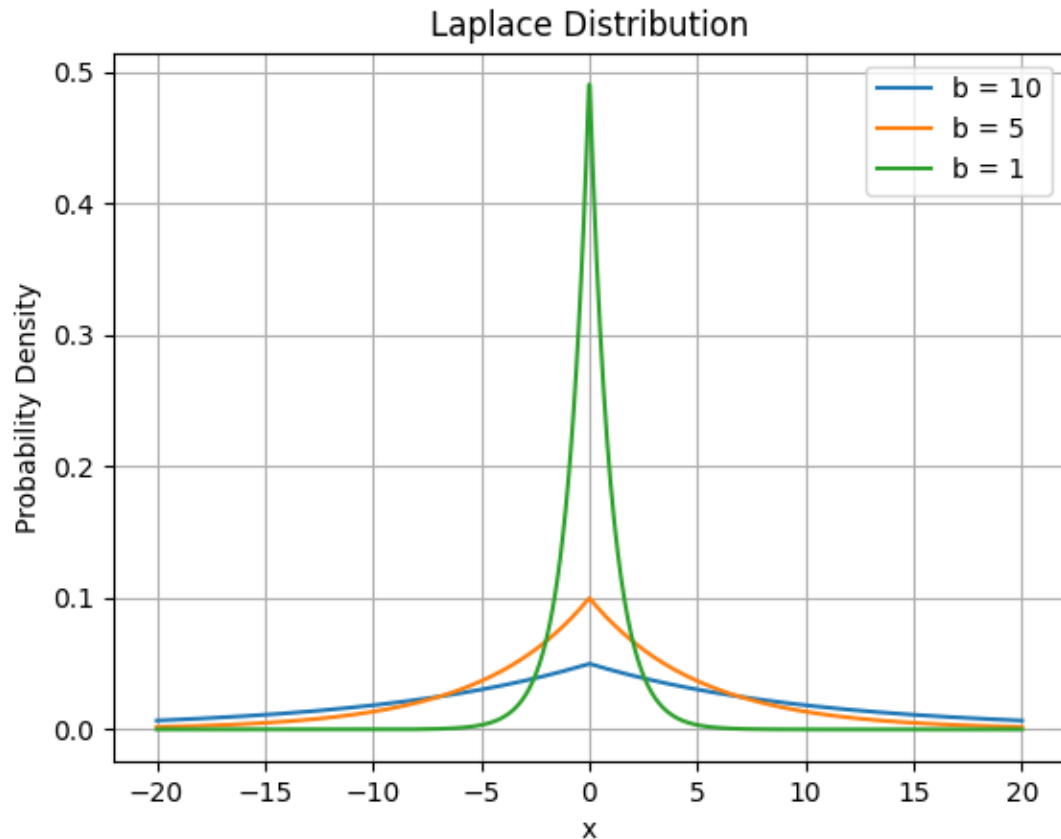
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- Proof: We can simplify $P\left(|M(G) - f(G)| \leq \frac{\Delta_f}{\epsilon} \log\left(\frac{1}{\delta}\right)\right) = P\left(\text{Lap}\left(\frac{\Delta_f}{\epsilon}\right) \leq \frac{\Delta_f}{\epsilon} \log\left(\frac{1}{\delta}\right)\right) = 1 - \exp\left(-\ln\left(\frac{1}{\delta}\right)\right) = 1 - \delta.$

By the Laplace distribution, we have that

$$P(|X| \geq bt) = \exp(-t)$$

Laplace Mechanism vs. Geometric Mechanism

- Symmetric geometric distribution PMF at $x \in Z$: $\frac{e^b - 1}{e^b + 1} \cdot e^{-|i| \cdot b}$



Laplace Mechanism vs. Geometric Mechanism

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 - For each fixed count query, there exists a geometric mechanism M^* such that **each** user derives as much utility as a mechanism optimally tailored to that user

Laplace Mechanism vs. Geometric Mechanism

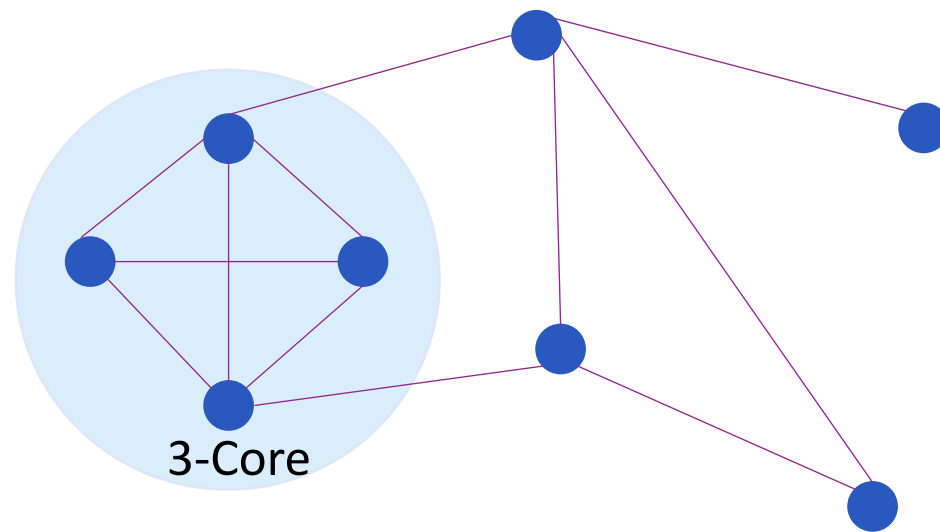
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Implementable on finite-bit computers!
[Balcer and Vadhan 2018]

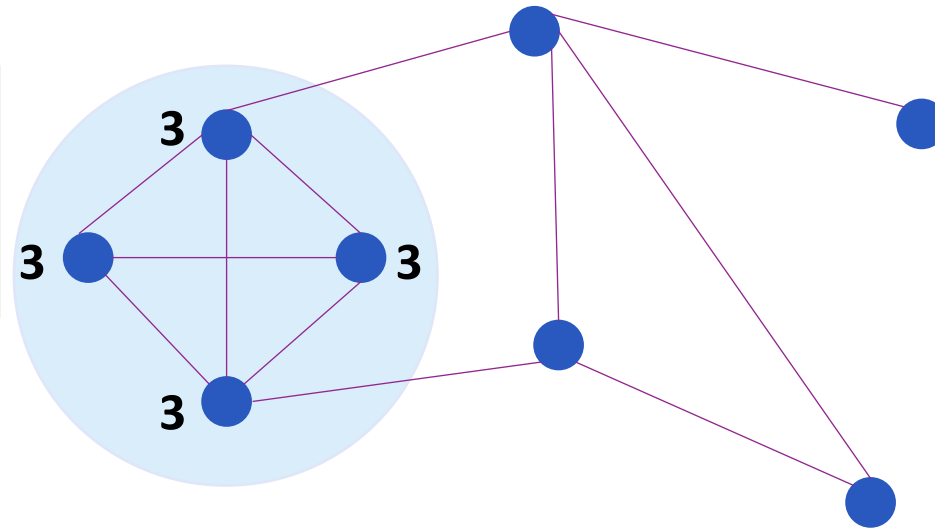
Next: Example of Geometric Mechanism that also gets **local privacy**

k -Core



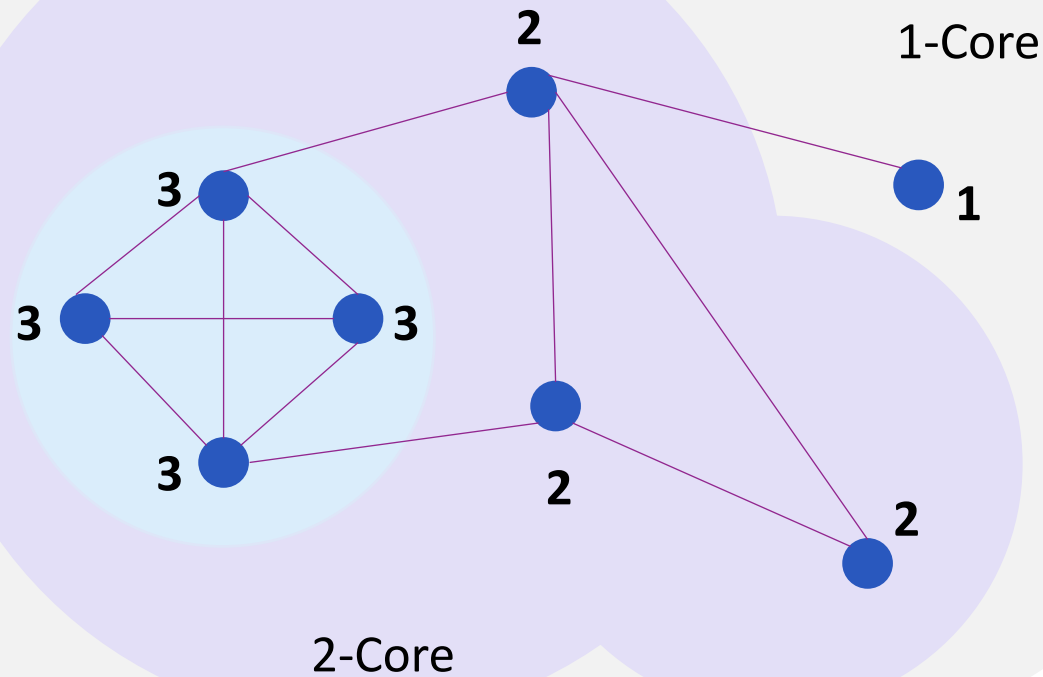
k -Core Decomposition

Core Number of Node v :
Maximum Core Value of
a Core Containing v

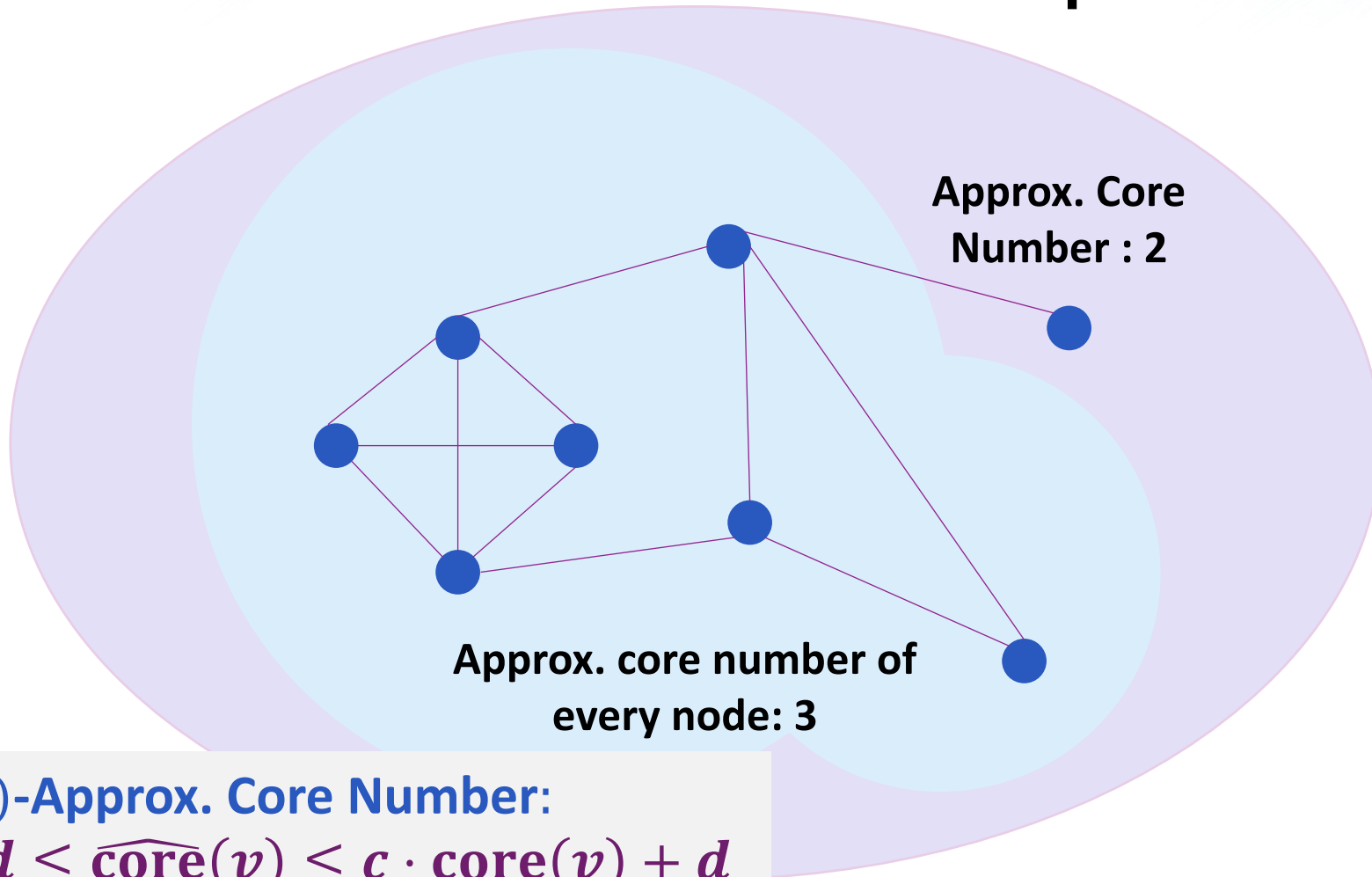


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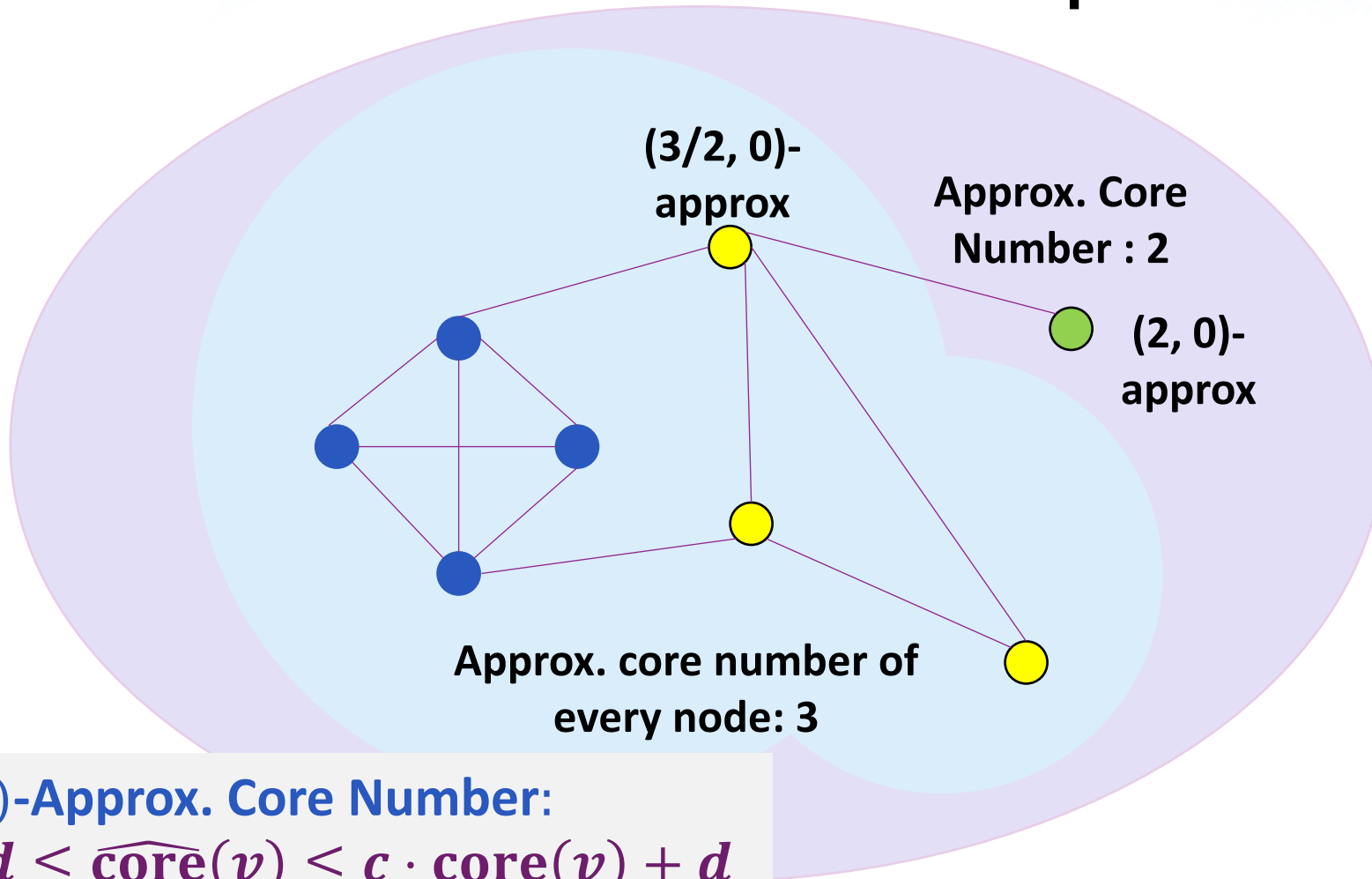
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Approximate k -Core Decomposition



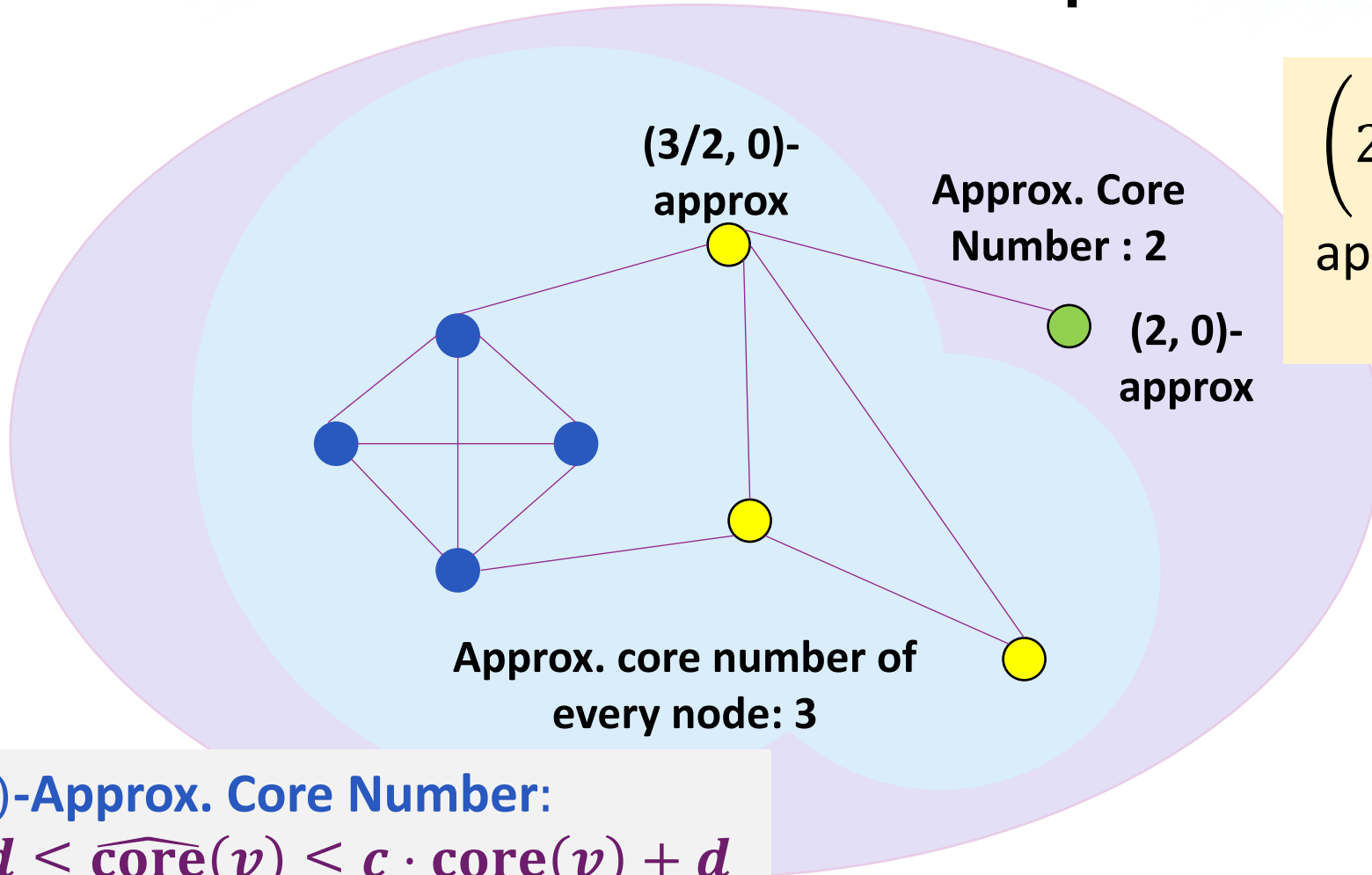
Approximate k -Core Decomposition



(c, d) -Approx. Core Number:

$$\text{core}(v) - d \leq \widehat{\text{core}}(v) \leq c \cdot \text{core}(v) + d$$

Approximate k -Core Decomposition



$\left(2 + \eta, O\left(\frac{\log^3(n)}{\epsilon}\right)\right)$ -
approximations in this
paper

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Level Data Structure and Core Numbers

Non-private sequential and parallel level data structures for dynamic problem:

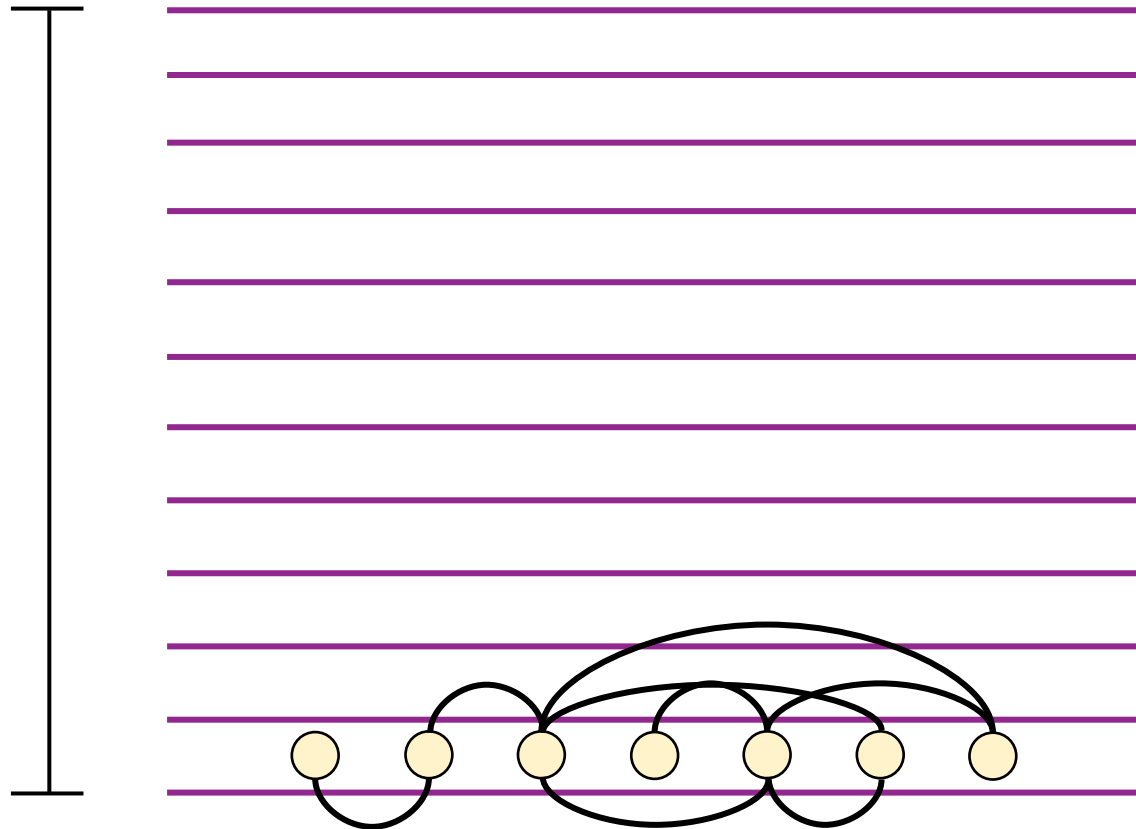
[Bhattacharya-Henzinger-Nanongkai-Tsourakakis '15;
Henzinger-Neumann-Wiese '20;
Liu-Shi-Yu-Dhulipala-Shun '22]

Level Data Structure and Core Numbers

In this example:

$$\eta = 0.1$$

$$4\log_{1+\eta}(n)$$



Move up if induced degree in **active** vertices $> (1 + \eta)$

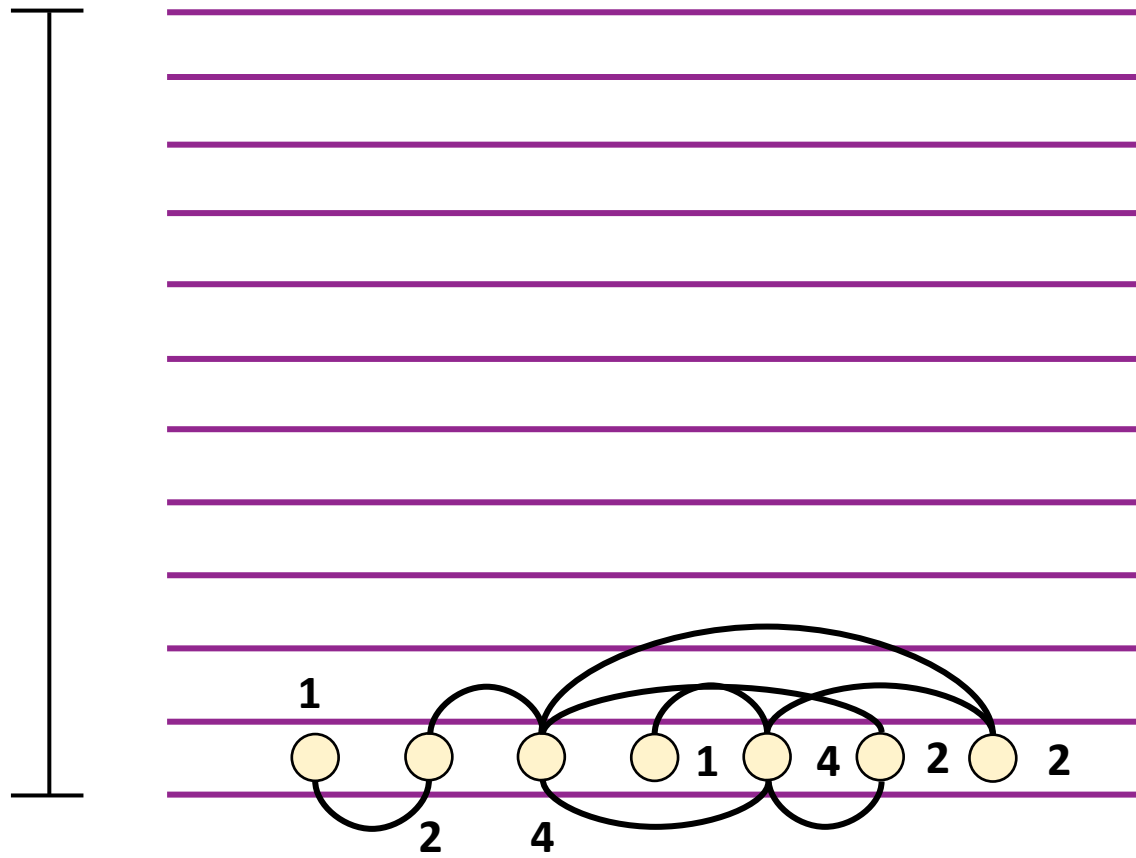
Initially all vertices are active

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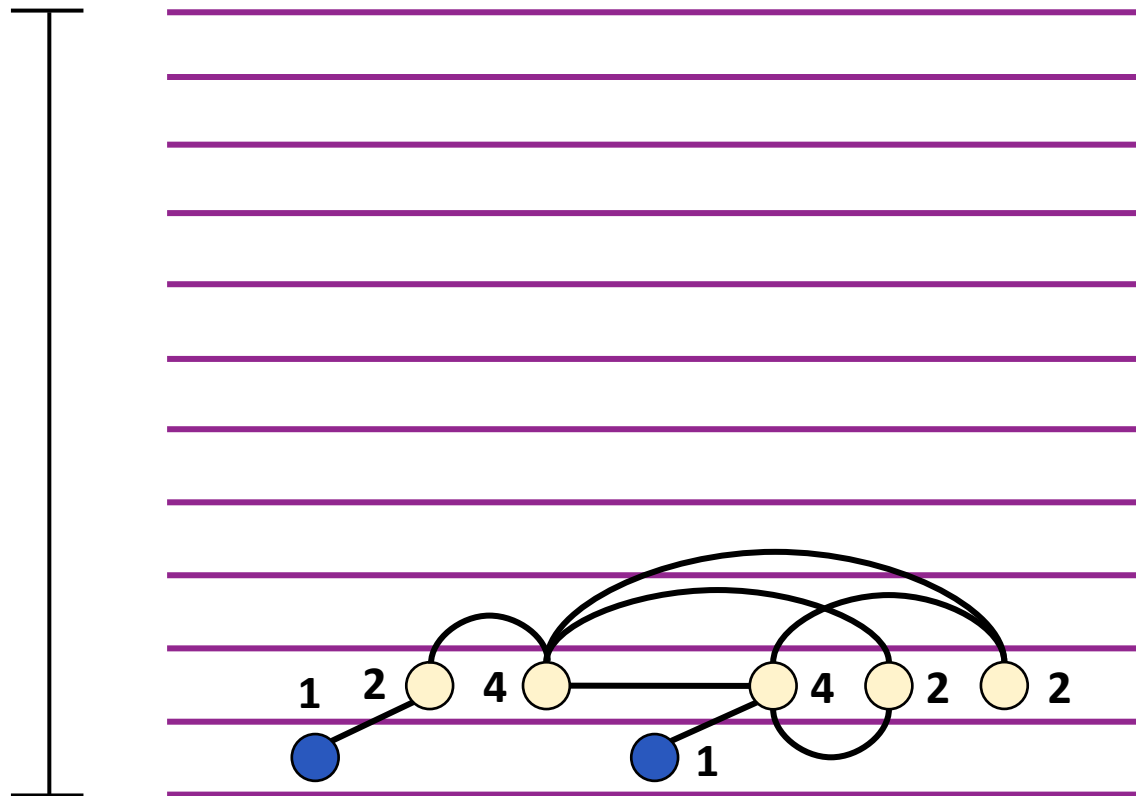
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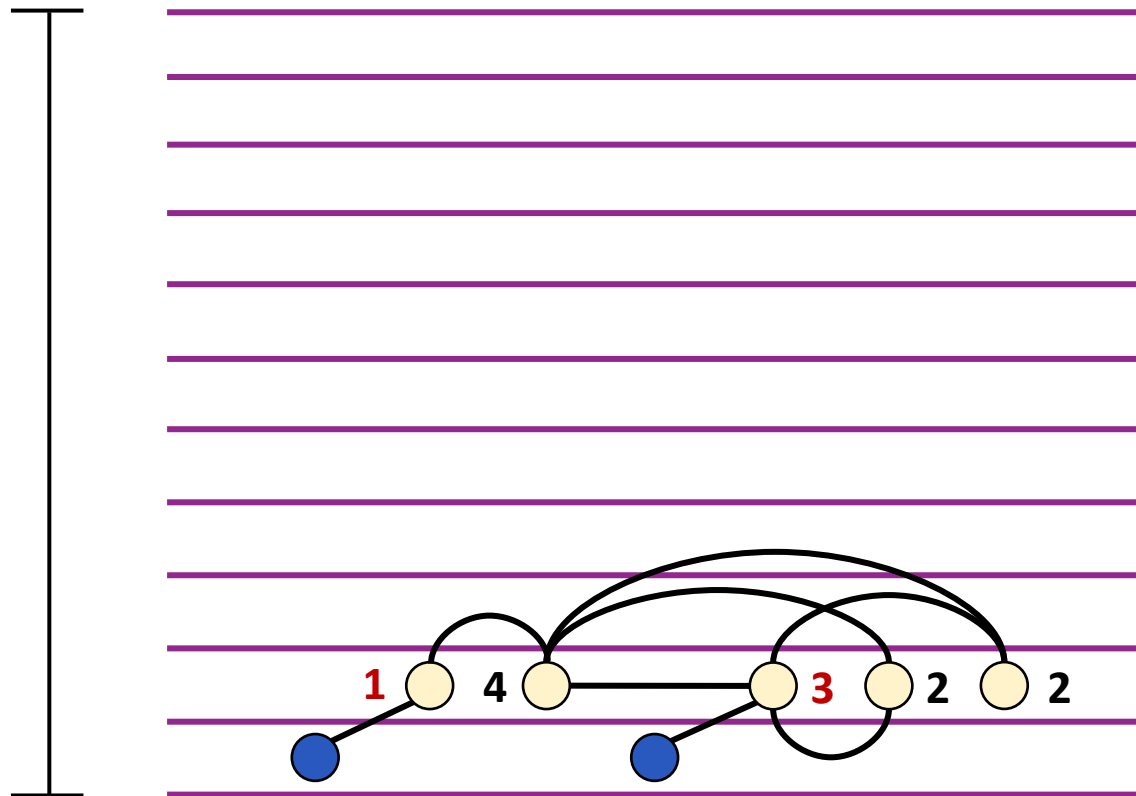
Vertices which **moved** remain **active**

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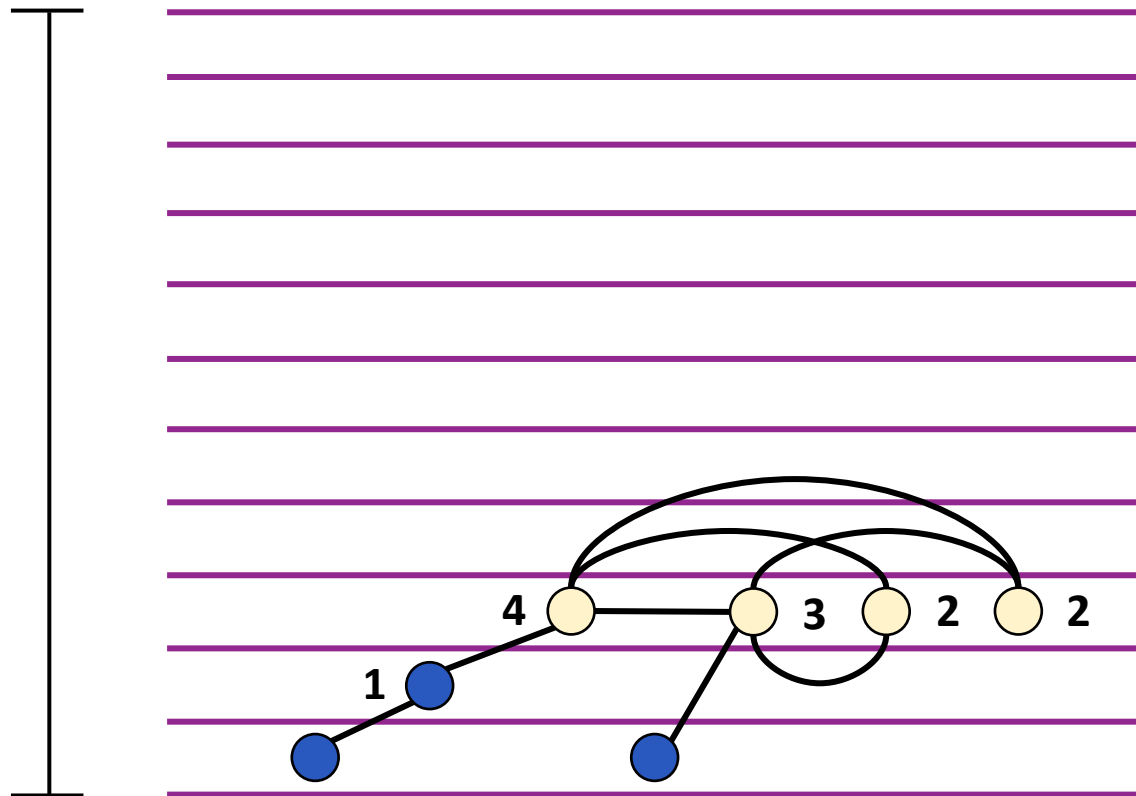
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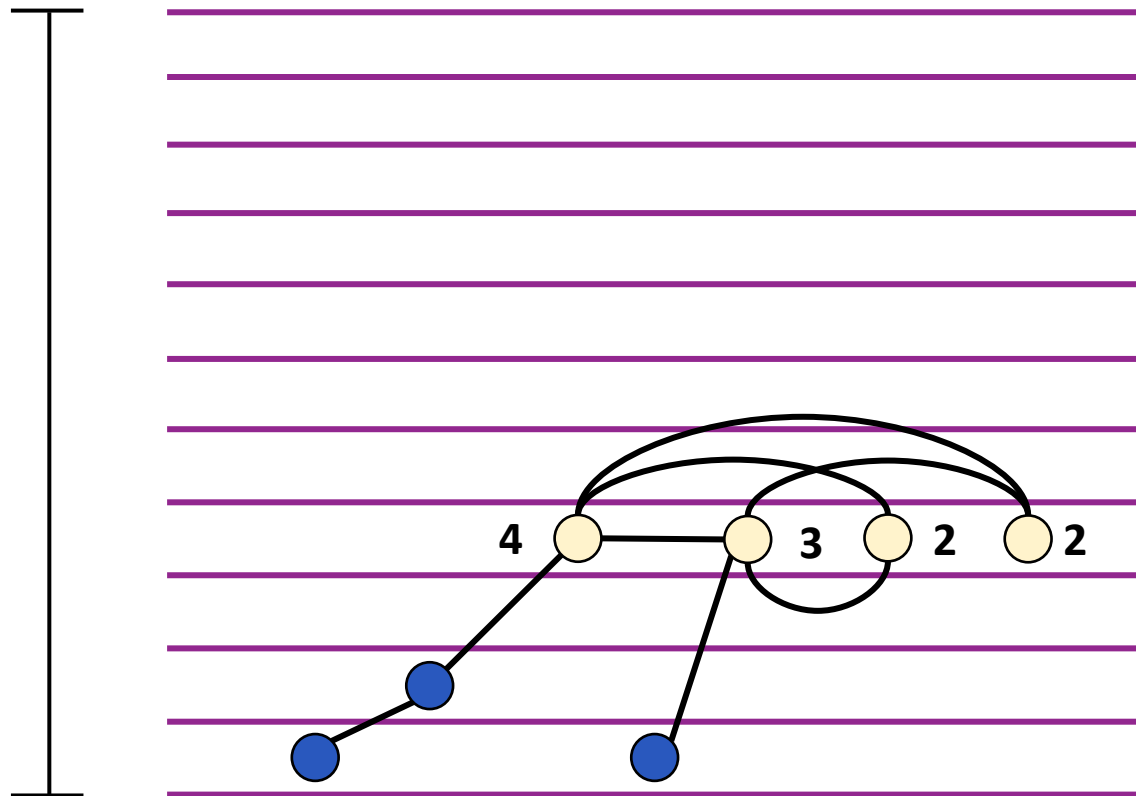
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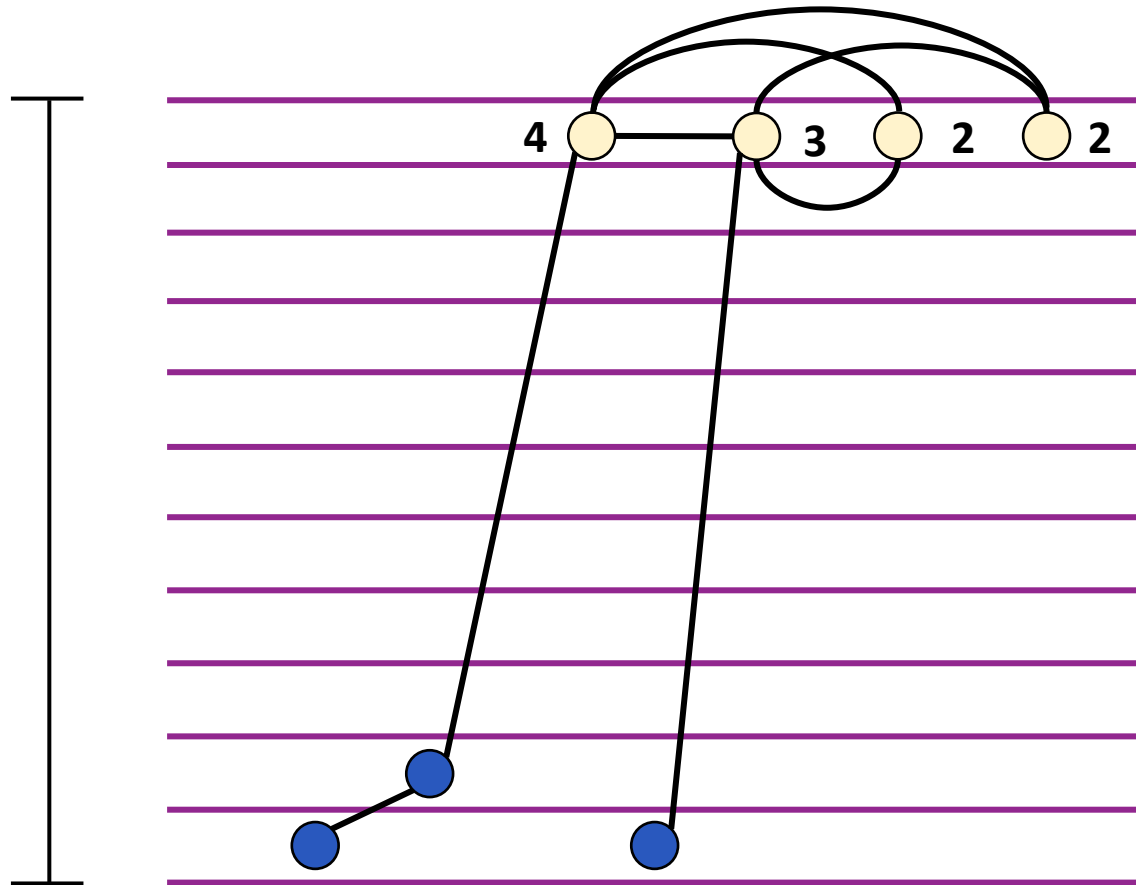
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Non-Private Core Number Approximation

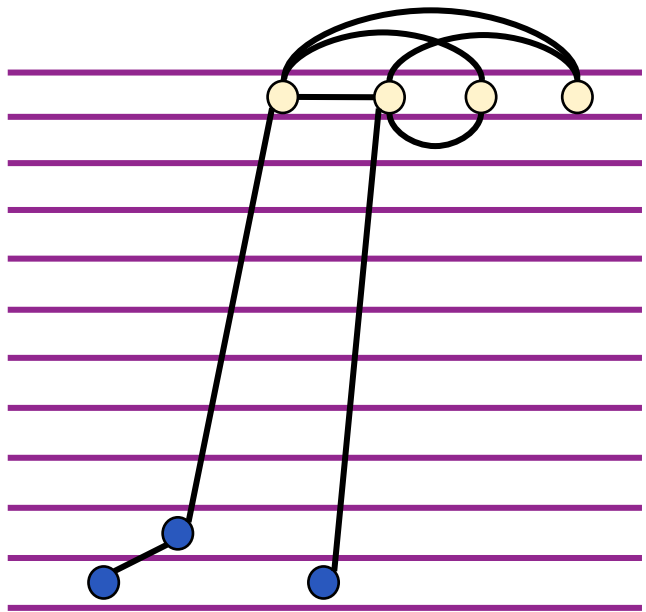
$$\eta = 0.1$$

Set cutoffs $(1 + \eta)^i$ for all $i \in [\log_{1+\eta}(n)]$

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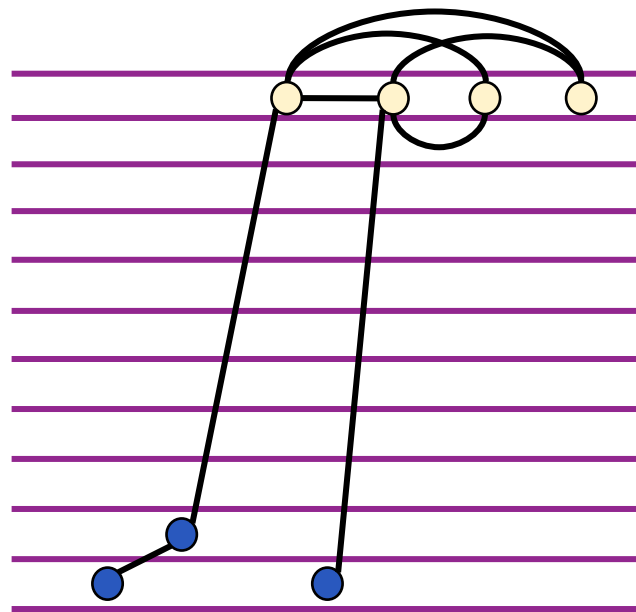
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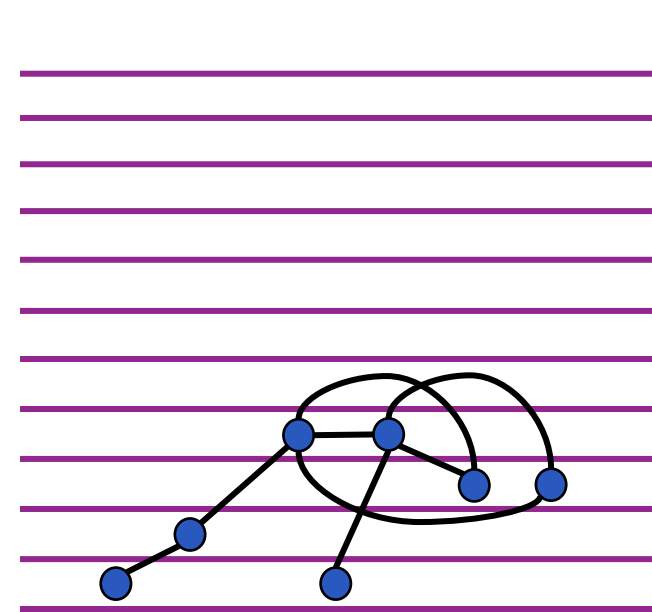
Cutoff: $(1 + \eta)$

...



Cutoff: $(1 + \eta)^7$

...



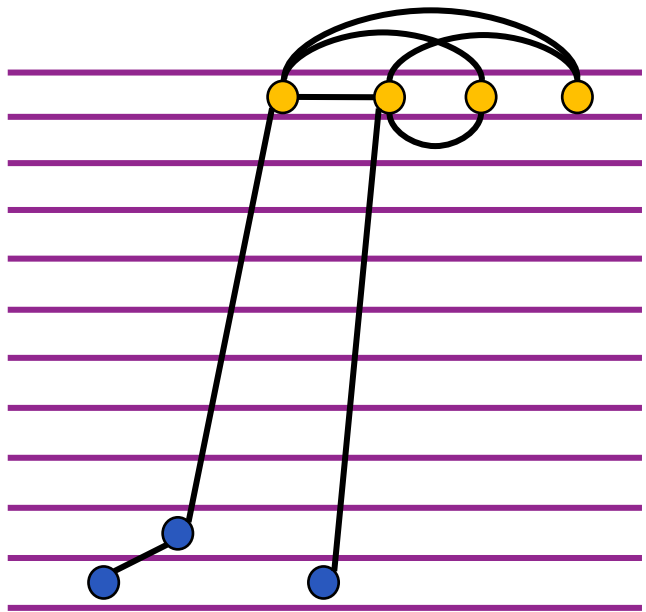
Cutoff: $(1 + \eta)^8$

Give approx core number $2 \cdot (1 + \eta)^i$
using **largest cutoff** where node is on the **topmost level**

Non-Private Core Number Approximation

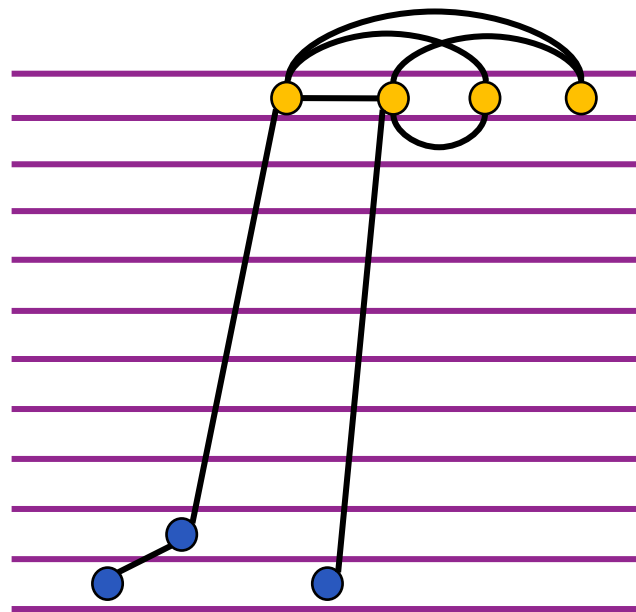
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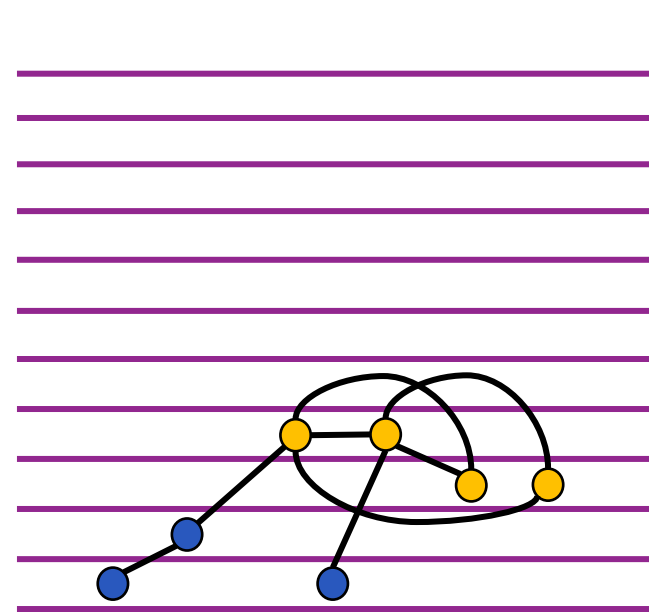
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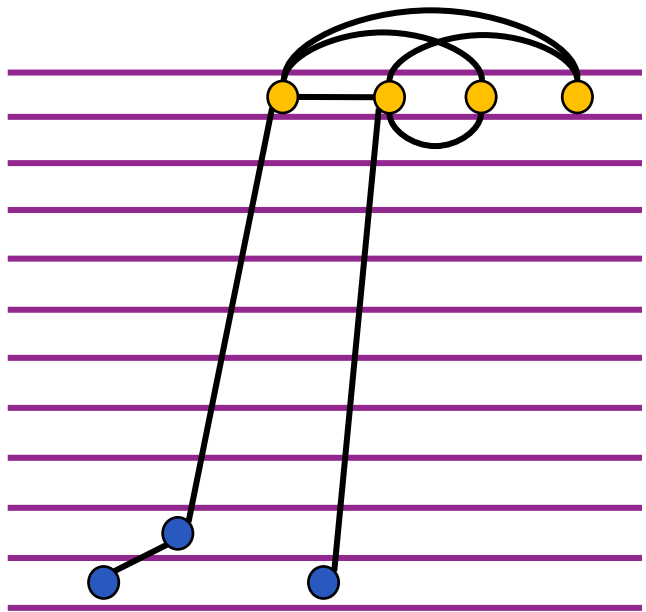
Cutoff: $(1 + \eta)^8$

$$\text{Approximation: } 2 \cdot (1 + \eta)^7 = 2 \cdot 1.1^7 = 2 \cdot 1.95 = 3.9$$

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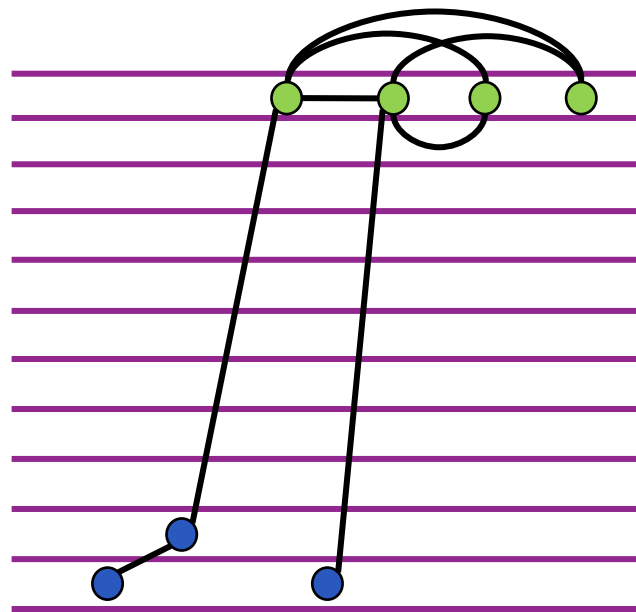
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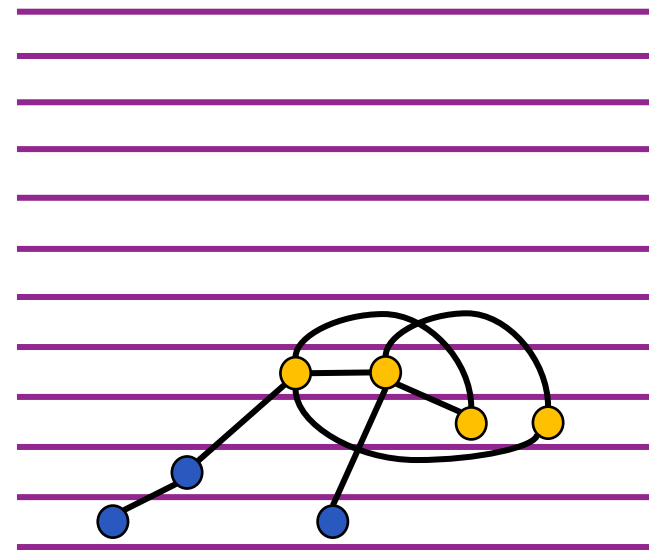


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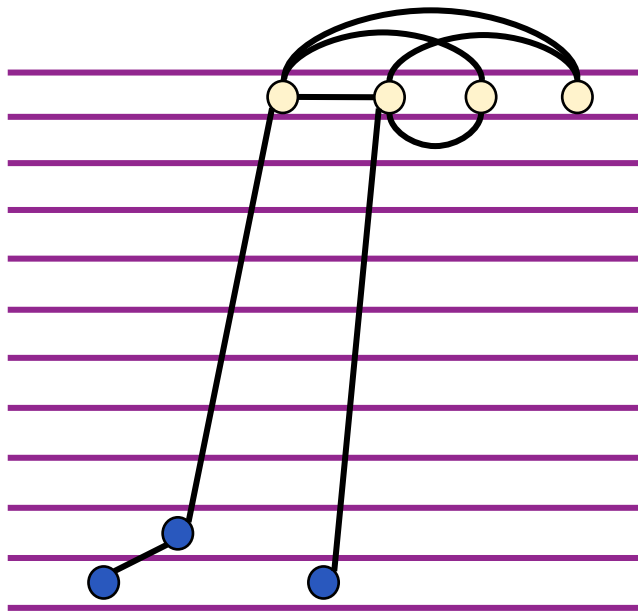
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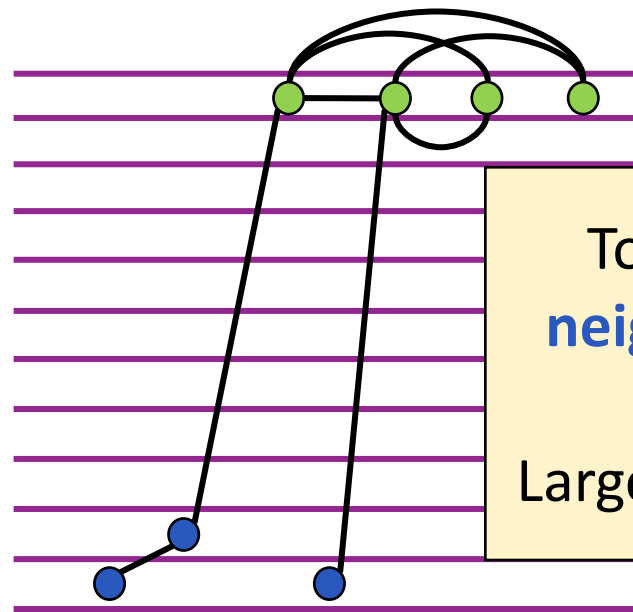
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Cutoff: $(1 + \eta)$

...



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Top level means adjacent to **many neighbors of sufficiently high degree**

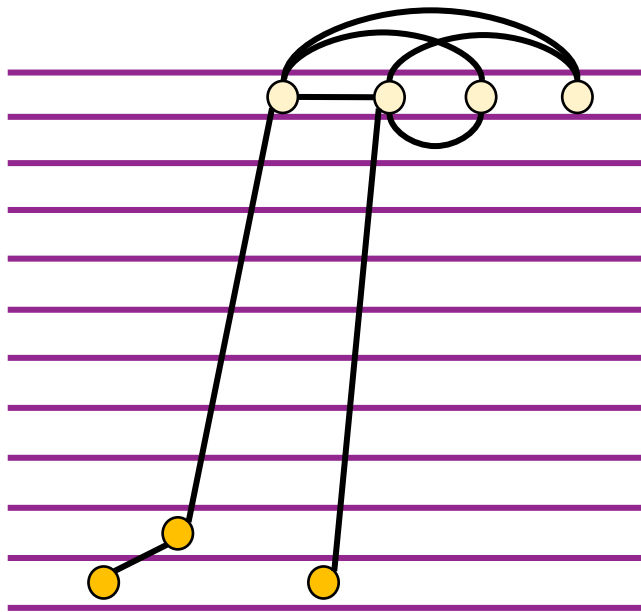
Largest cutoff gives **largest such degree**

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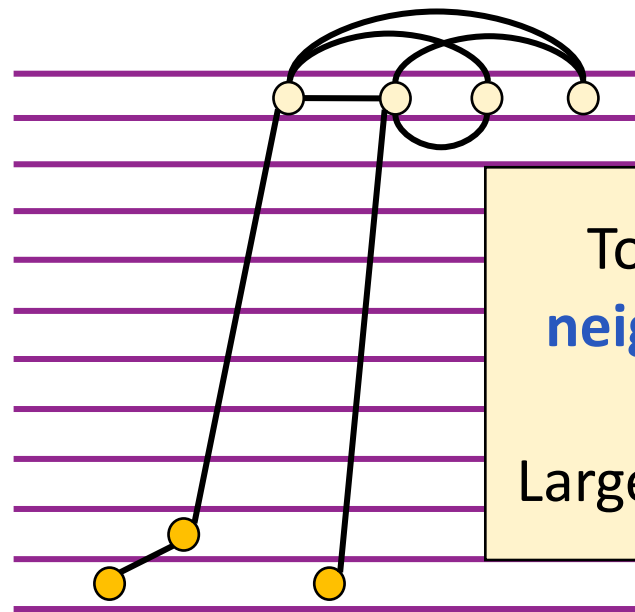
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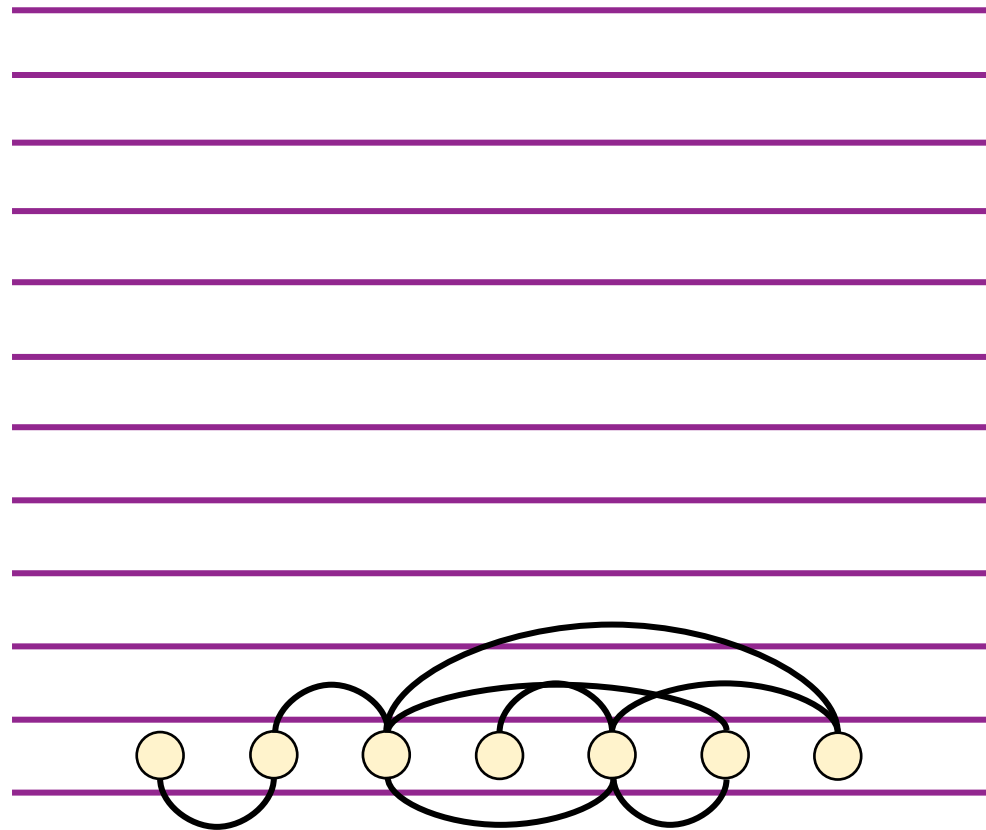
Approximation: **1**

ϵ -LEDP Core Numbers

Each **active vertex** draws **i.i.d. noise** from **symmetric geometric distribution**

Distribution ***Geom*(b)**

$$\text{PMF: } \frac{e^b - 1}{e^b + 1} \cdot e^{-|X| \cdot b}$$



Release and move up degree **+ noise** in **active** vertices $> (1 + \eta)$

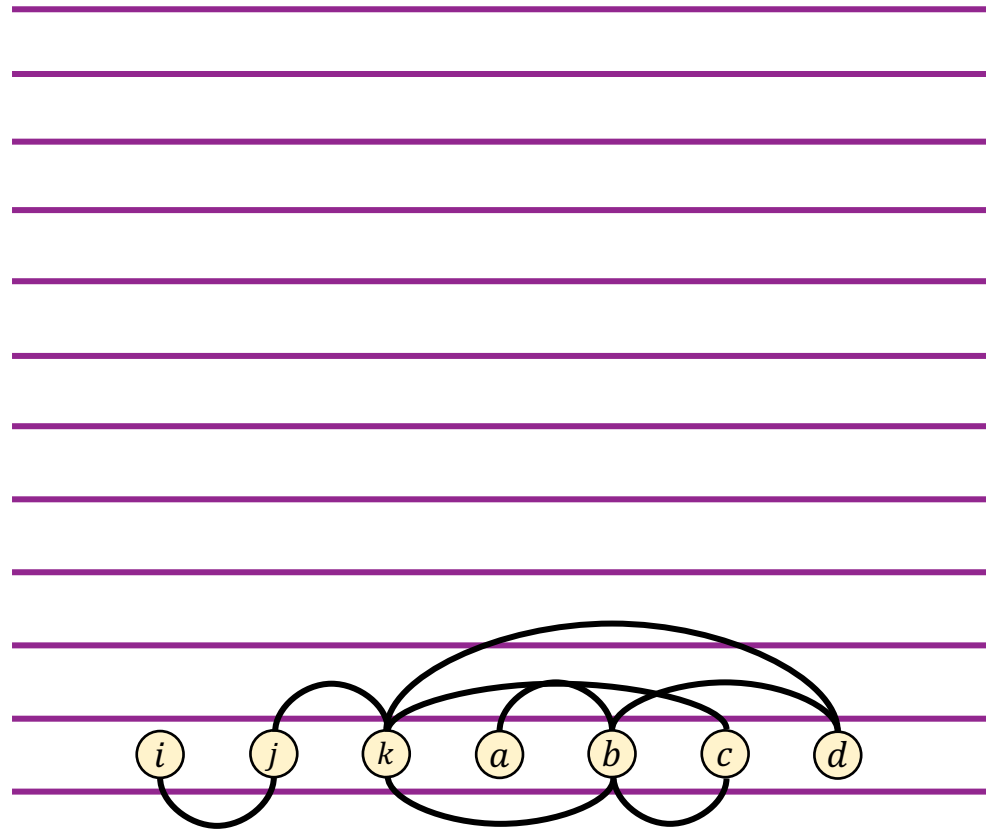
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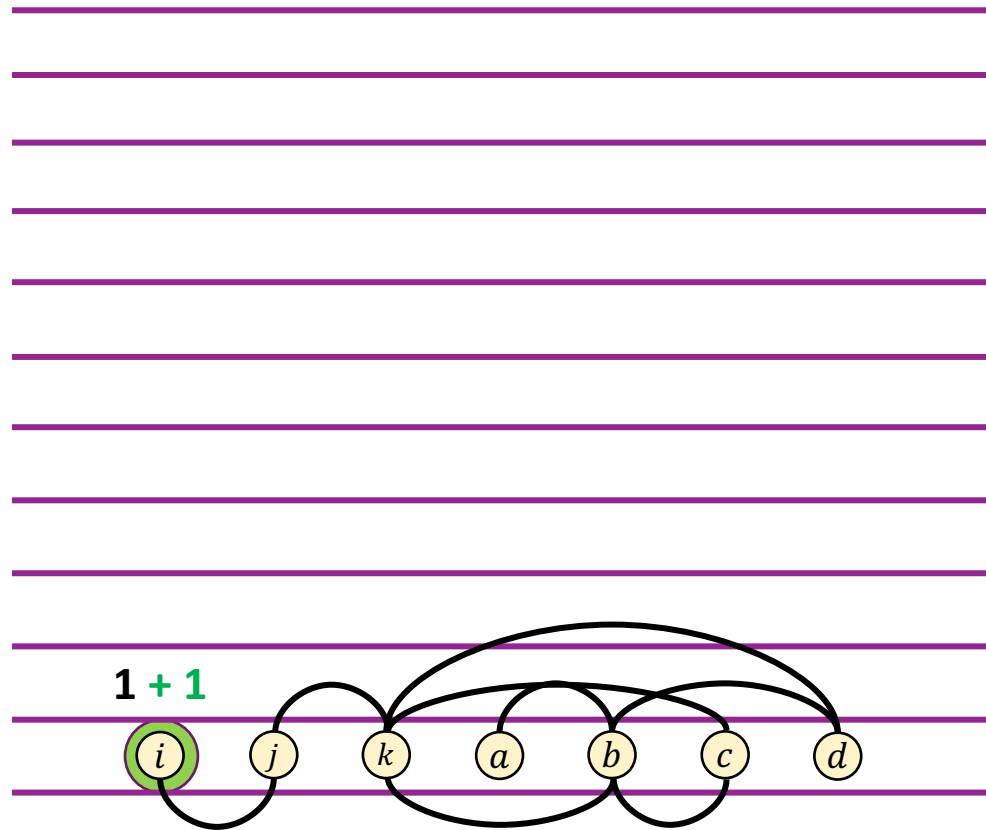
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move up

$$\text{Where } N_i \sim \text{Geom} \left(\frac{\epsilon}{8 \log_{1+\eta}^2(n)} \right)$$



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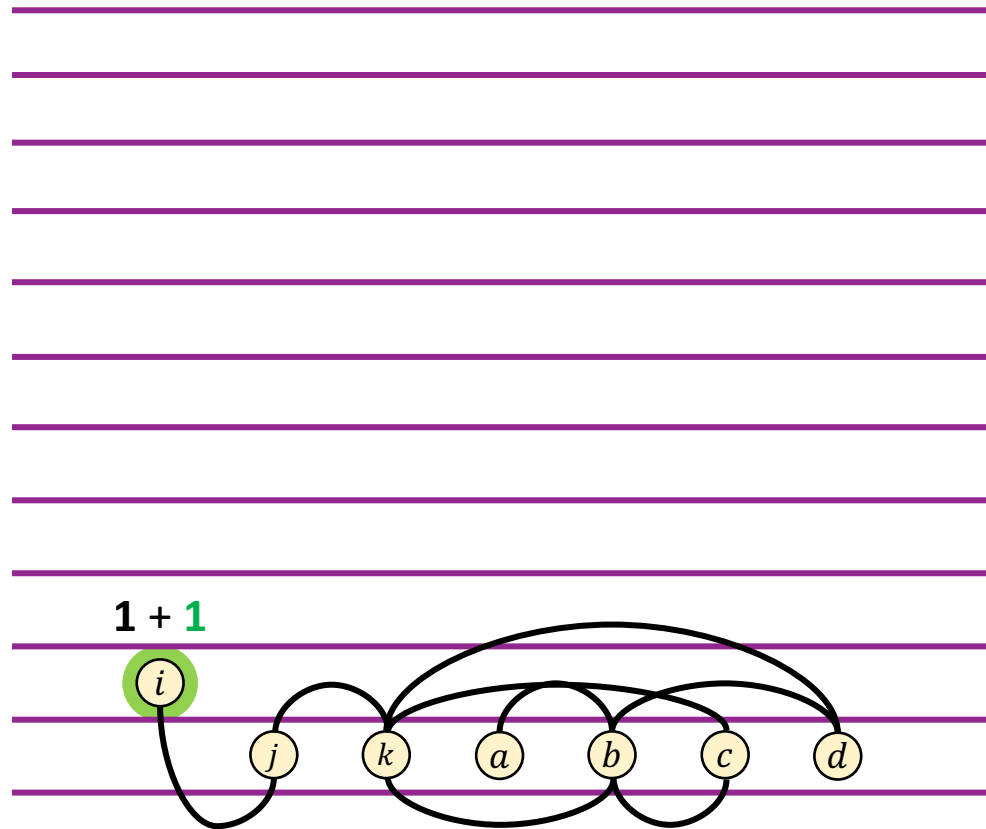
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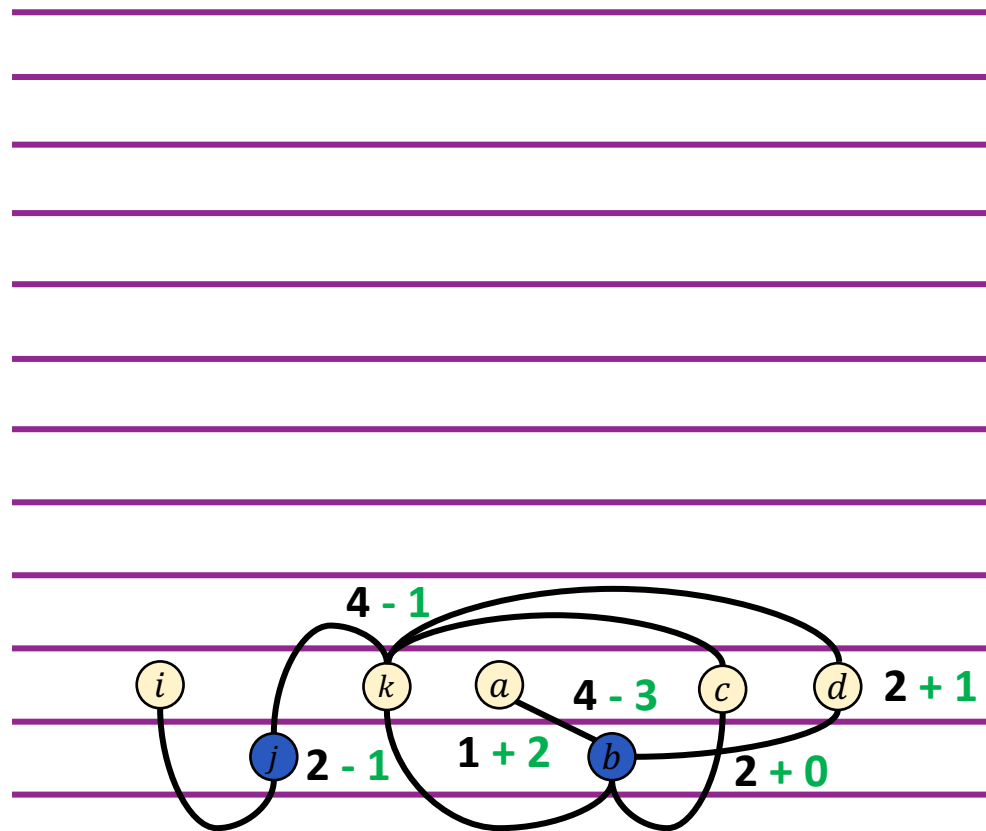
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Redraw new noise each time vertex remains active

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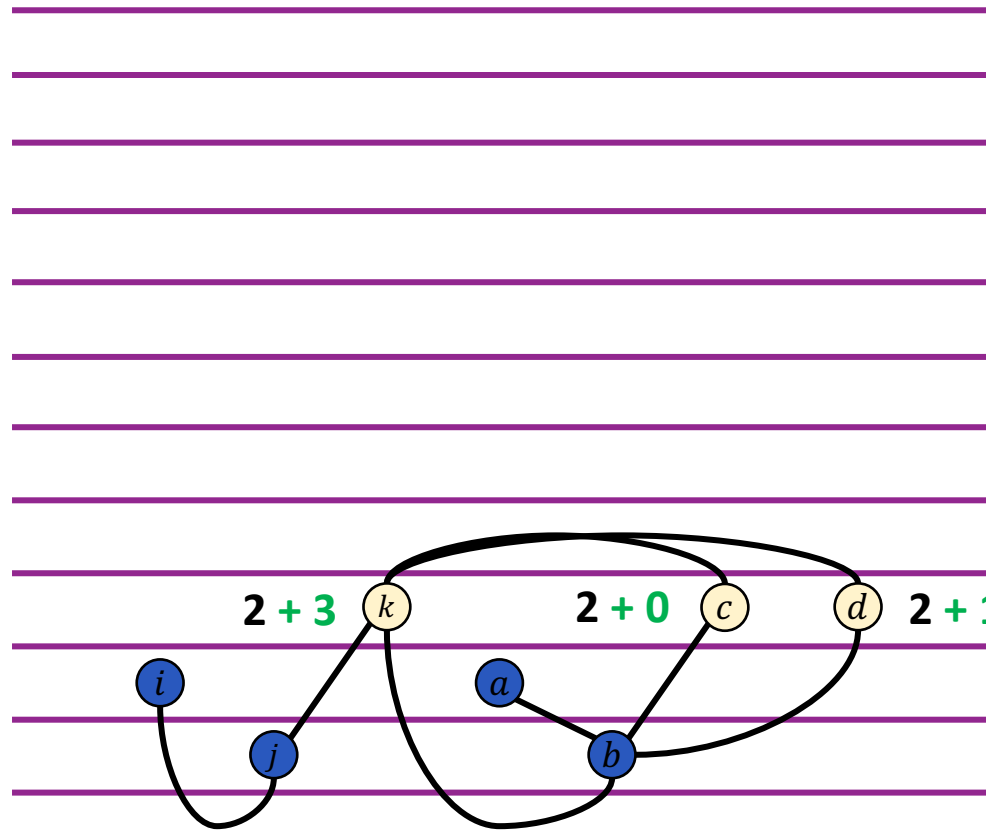
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Approx. as before $2(1 + \eta)^i$ using topmost level

ϵ -LEDP Core Numbers

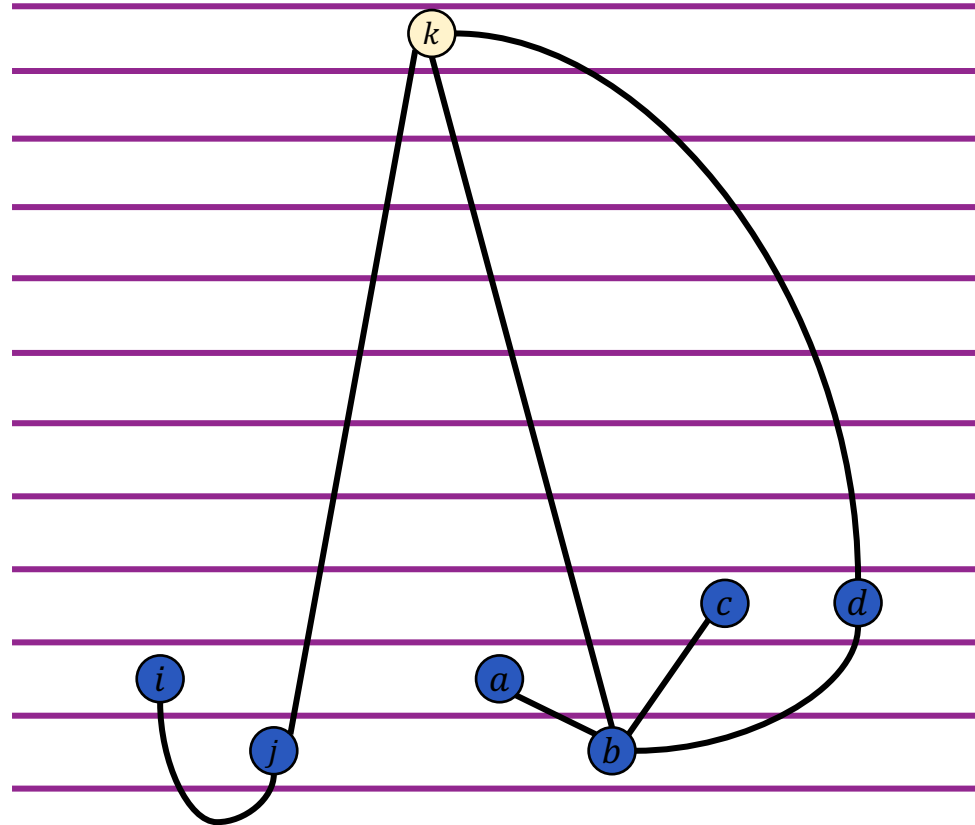
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Distribution **$Geom(b)$**

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If **$\deg(k) + N_k > (1 + \eta)$** ,
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Where $N_k \sim Geom\left(\frac{\epsilon}{8 \log_{1+\eta}^2(n)}\right)$



Release and move up degree **+ noise** in **active** vertices $> (1 + \eta)$

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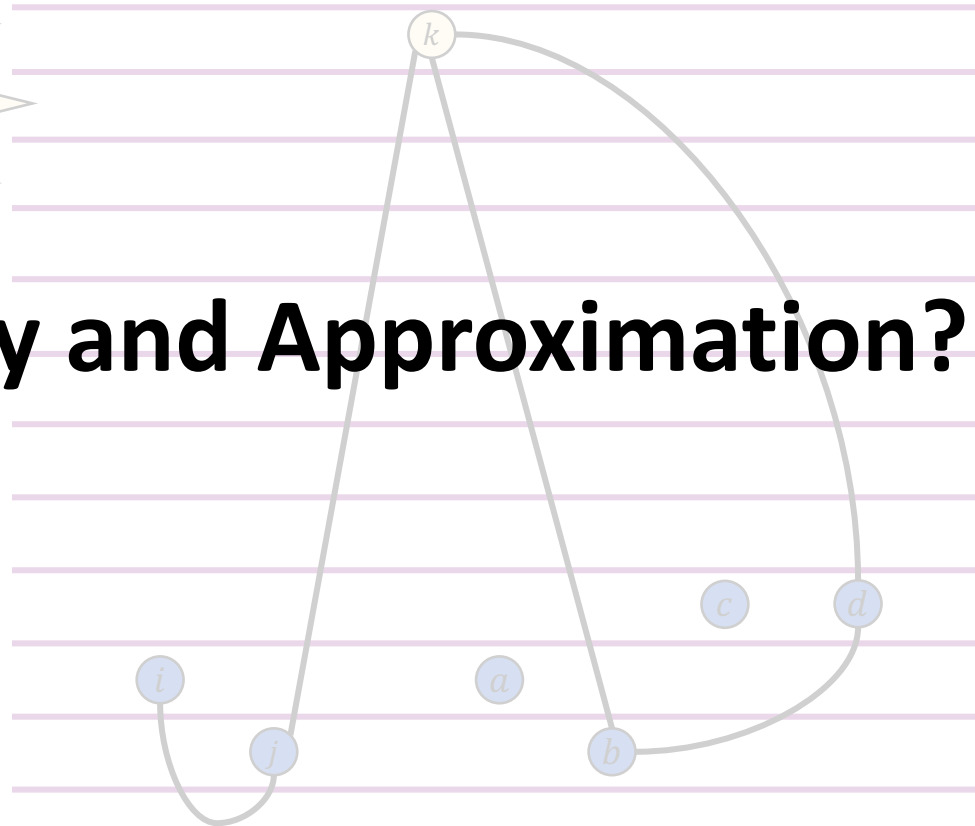
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$$\text{Where } N_k \sim \text{Geom}\left(\frac{\epsilon}{8 \log_{1+\eta}(n)}\right)$$

Privacy and Approximation?



Move up if induced degree **+ noise** in **active** vertices $> (1 + \eta)$

Redraw new noise each time vertex remains active and determines whether move up

Approx. as before $2(1 + \eta)^i$ where i largest that vertex is on the topmost level

Privacy Proof

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- R takes as **input \mathbf{a} (adjacency list)** and **public set of active vertices A**
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Global Sensitivity:

$$\Delta_f = \max_{\text{edge-neighbors } G \text{ and } G'} |f(G) - f(G')|$$

$$f(\mathbf{a}, A) = |\mathbf{a} \cap A|$$

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Geometric Mechanism:

[Chan-Shi-Song '11; Balcer-Vadhan '18]

$$M(\mathbf{a}, A) = f(\mathbf{a}, A) + \text{Geom}\left(\frac{\epsilon}{\Delta_f}\right)$$

M is ϵ -DP

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- Same LR called for all vertices $4\log_{1+\eta}^2(n)$ times

Privacy Proof

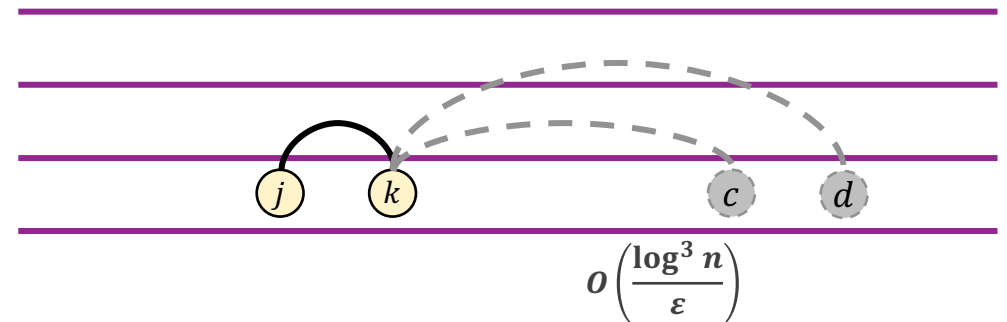
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- Same LR called for all vertices $4\log_{1+\eta}^2(n)$ times
- For each edge, called $8\log_{1+\eta}^2(n)$; then, $8\log_{1+\eta}^2(n) \cdot \frac{\epsilon}{8\log_{1+\eta}^2(n)} = \epsilon$ and so ϵ -LEDP

Approximation Proof Sketch

- With high probability, magnitude of each drawn noise is **upper bounded by**
 $O\left(\frac{\log^3 n}{\varepsilon}\right)$

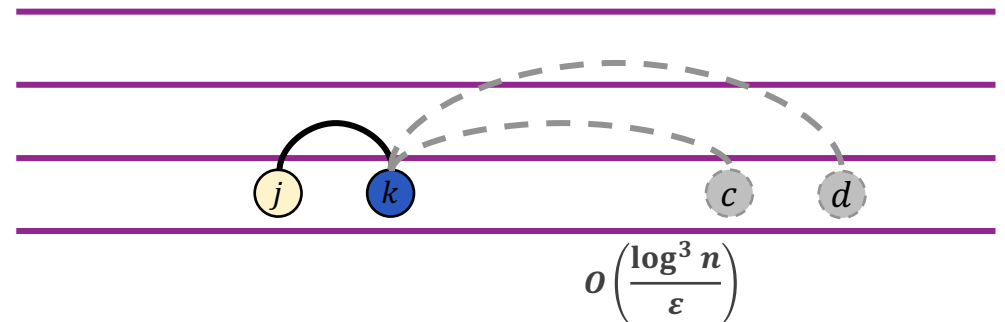
Approximation Proof Sketch

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- **Degree Upper Bound:** If a vertex v is on level $i < 4\log_{1+\eta}(n)$ at end of algorithm, then it has **at most** $(1 + \eta)^i + O\left(\frac{\log^3 n}{\varepsilon}\right)$ **neighbors on levels $\geq i$**



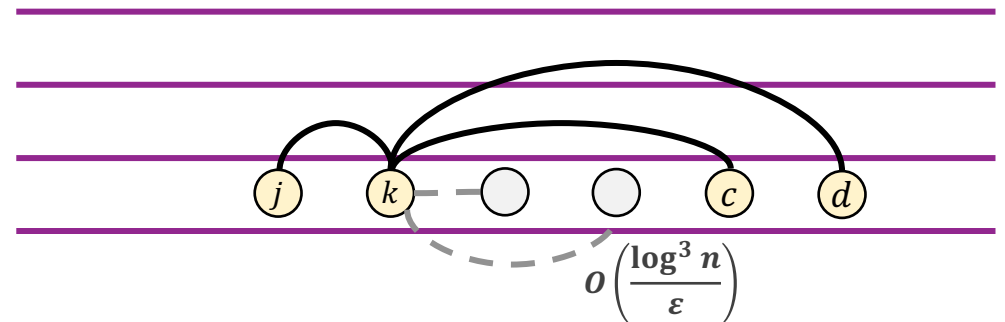
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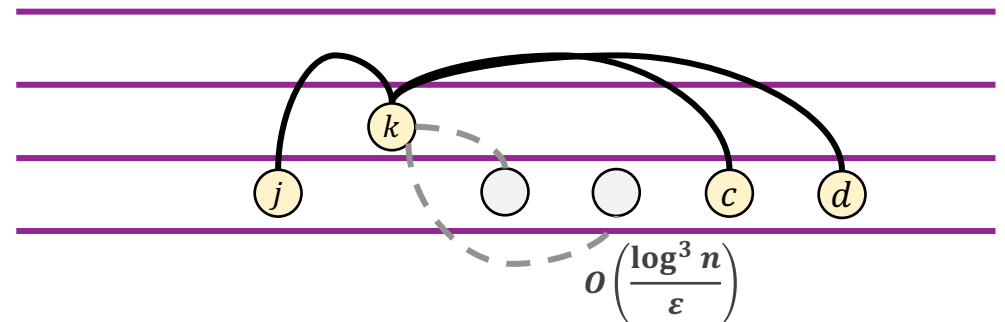
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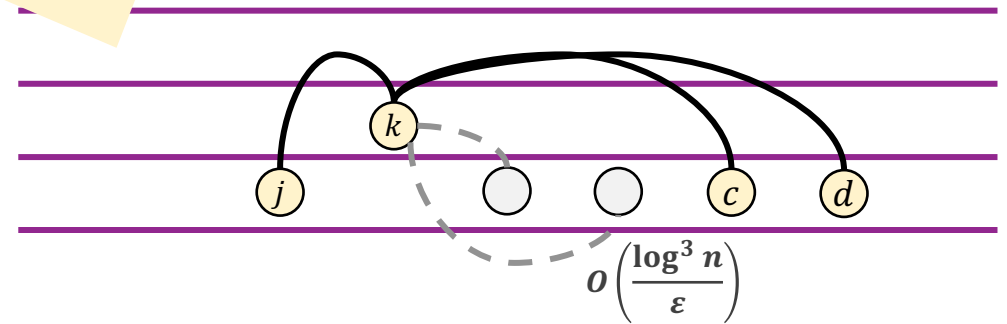
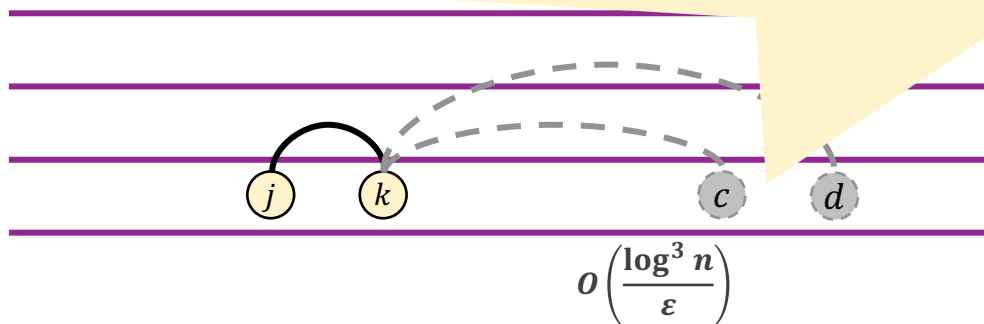
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Approximation Proof Sketch

Key: Largest cutoff
increases/decreases
by **additive** $O\left(\frac{\log^3 n}{\epsilon}\right)$



Approximation Proof Sketch

Recently improved
to $O\left(\frac{\log(n)}{\epsilon}\right)$

Key: Largest cutoff
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